## Due giorni di Algebra Lineare Numerica

## Structured matrices in the computation of band spectra of photonic crystals

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## Photonic Crystal: What is it?


periodic in one direction

periodic in two directions

$■$ Photonic crystals are dielectric media whose dielectric constant $\varepsilon(\mathbf{x})$, with $\mathbf{x} \in \mathbb{R}^{3}$, satisfies the periodicity condition

$$
\varepsilon\left(\mathbf{x}+m_{1} \mathbf{a}_{1}+m_{2} \mathbf{a}_{2}+m_{3} \mathbf{a}_{3}\right)=\varepsilon(\mathbf{x})
$$

for certain linearly independent vectors $\mathbf{a}_{1}, \mathbf{a}_{2}, \mathbf{a}_{3} \in \mathbb{R}^{3}$, where $m_{1}, m_{2}$ and $m_{3}$ are arbitrary integers.
■ The periodicity of the dielectric constant $\varepsilon(\mathbf{x})$ causes optical properties which are similar to the electronic properties for semiconductor crystals with a periodic potential.
■ Photonic crystals exhibit frequency intervals where incident light can propagate (bands) and frequency intervals in which incident light cannot propagate (band-gaps).

## Physical Assumptions

In order to study photonic crystals we have to refer to Maxwell's equations and cast them into the photonic crystals frame.

- Isotropy and linearity yield

$$
\mathbf{D}=\varepsilon(\mathbf{r}) \mathbf{E}, \quad \mathbf{B}=\mu(\mathbf{r}) \mathbf{H}
$$

- Magnetic permeability constant $(\mu(\mathbf{r}) \simeq 1): \mathbf{B}=\mathbf{H}$.

■ Lossless media: $\varepsilon(\boldsymbol{r}): \mathbb{R}^{3} \rightarrow \mathbb{R}$

- In a photonic crystal we don't have free charge $(\rho=0)$ and free current $(\mathbf{J}=0)$.
- We seek time-harmonic modes:

$$
\begin{equation*}
\mathbf{H}(\mathbf{r}, t)=\mathbf{H}(\mathbf{r}) e^{i \omega t}, \quad \mathbf{E}(\mathbf{r}, t)=\mathbf{E}(\mathbf{r}) e^{i \omega t} \tag{2}
\end{equation*}
$$

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■ Isotropy and linearity yield:

$$
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$$

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$$

## Maxwell's Equations for photonic crystals

Maxwell equations, which govern light transmission in photonic crystals, reduce to the following system of equations:

$$
\begin{aligned}
\nabla \cdot[\varepsilon \mathbf{E}] & =0, & & \text { [Coulomb's law] } \\
\nabla \times \mathbf{H}-i \sqrt{\eta} \varepsilon \mathbf{E} & =0, & & \text { [Ampère's law] } \\
\nabla \times \mathbf{E}+i \sqrt{\eta} \mathbf{H} & =0, & & \text { [Faraday's law] } \\
\nabla \cdot \mathbf{H} & =0, & & \text { [Absence of free magnetic poles] }
\end{aligned}
$$

where $\sqrt{\eta}=\frac{\omega}{c}$.

```
We apply Bloch's theorem: E(x)= i}\mp@subsup{e}{}{ik\cdotx}\mathcal{E}(x),H(x)=\mp@subsup{e}{}{ik\cdotx}\mathcal{H}(x)\mathrm{ , where
\mathcal{E}(x+m
H}(\mathbf{x}+\mp@subsup{m}{1}{}\mp@subsup{\mathbf{a}}{1}{}+\mp@subsup{m}{2}{}\mp@subsup{\mathbf{a}}{2}{}+\mp@subsup{m}{3}{}\mp@subsup{\mathbf{a}}{3}{})=\mathcal{H}(\mathbf{x})\mathrm{ , we get:
```

$\nabla \cdot[\varepsilon(x) \mathcal{E}(x)]+i k \cdot[\varepsilon(x) \mathcal{E}(x)]=0$,
$\nabla \times \mathcal{H}(\mathrm{x})+i[\mathrm{k} \times \mathcal{H}(\mathrm{x})]-i \sqrt{\eta} \varepsilon(\mathrm{x}) \mathcal{E}(\mathrm{x})=0$.
$\nabla \times \mathcal{E}(\mathbf{x})+i[\mathbf{k} \times \mathcal{E}(\mathbf{x})]+i \sqrt{\eta} \varepsilon(\mathbf{x}) \mathcal{H}(\mathbf{x})=0$,
$\nabla \cdot[\mathcal{H}(\mathrm{x})]+i \mathbf{k} \cdot \mathcal{H}(\mathrm{x})=0$.

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where $\sqrt{\eta}=\frac{\omega}{c}$.
We apply Bloch's theorem: $\mathbf{E}(\mathbf{x})=e^{i \mathbf{k} \cdot \mathbf{x}} \mathcal{E}(\mathbf{x}), \mathbf{H}(\mathbf{x})=e^{i \mathbf{k} \cdot \mathbf{x}} \mathcal{H}(\mathbf{x})$, where $\mathcal{E}\left(\mathbf{x}+m_{1} \mathbf{a}_{1}+m_{2} \mathbf{a}_{2}+m_{3} \mathbf{a}_{3}\right)=\mathcal{E}(\mathbf{x})$ and $\mathcal{H}\left(\mathbf{x}+m_{1} \mathbf{a}_{1}+m_{2} \mathbf{a}_{2}+m_{3} \mathbf{a}_{3}\right)=\mathcal{H}(\mathbf{x})$, we get:

$$
\begin{aligned}
& \nabla \cdot[\varepsilon(\mathbf{x}) \mathcal{E}(\mathbf{x})]+i \mathbf{k} \cdot[\varepsilon(\mathbf{x}) \mathcal{E}(\mathbf{x})]=0 \\
& \nabla \times \mathcal{H}(\mathbf{x})+i[\mathbf{k} \times \mathcal{H}(\mathbf{x})]-i \sqrt{\eta} \varepsilon(\mathbf{x}) \mathcal{E}(\mathbf{x})=0, \\
& \nabla \times \mathcal{E}(\mathbf{x})+i[\mathbf{k} \times \mathcal{E}(\mathbf{x})]+i \sqrt{\eta} \varepsilon(\mathbf{x}) \mathcal{H}(\mathbf{x})=0 \\
& \nabla \cdot[\mathcal{H}(\mathbf{x})]+i \mathbf{k} \cdot \mathcal{H}(\mathbf{x})=0
\end{aligned}
$$

## 2D: TE and TM Modes

When $k_{z}=0$, the modes of every two-dimensional photonic crystal can be classified into two distinct polarizations: either ( $H_{x}, H_{y}, E_{z}$ ) or $\left(E_{x}, E_{y}, H_{z}\right)$.


Figura: TM mode: the magnetic field is confined to the $x y$ plane.


Figura: TE mode: the electric field is confined to the $x y$ plane.

## 2D: TE and TM Eigenvalue Equations

In the TM mode we have to study spectral eigenvalue problem for the Helmholtz equation

$$
\begin{equation*}
-\left(\frac{\partial^{2} \psi}{\partial^{2} x}+\frac{\partial^{2} \psi}{\partial^{2} y}\right)=\eta \varepsilon(x, y) \psi \tag{3}
\end{equation*}
$$

and in the TE mode we have to solve the following

$$
\begin{equation*}
-\nabla \cdot\left(\frac{1}{\varepsilon(x, y)} \nabla \psi\right)=\eta \psi \tag{4}
\end{equation*}
$$

(where $\varepsilon(x, y)=n^{2}(x, y)$ ). In (3) the electric field is given by $(0,0, \psi(x, y))^{T}$, whereas in (4) the magnetic field is given by $(0,0, \psi(x, y))^{T}$. The main goal is to find the eigenvalues $\eta$.

## Photonic Crystals in 2 Dimensions

Basically, we study two numerical methods for the following two cases:


As an example, in the connected case:


## Prevailing Numerical Methods

Time Domain Methods

1) Plane Wave Expansion (PWE) Method;
2) Finite Difference Time Domain (FDTD) Method.

## Frequency Domain Methods

1) Finite difference frequency domain (FDFD) method;
2) Fourier expansion (FE) method;
3) Finite element frequency domain (FEFD) method.

## FDFD Method

■ We get the 2-D (modified) Helmholtz equations for TE modes

$$
\begin{equation*}
-\nabla \cdot\left(\frac{1}{\varepsilon} \nabla \phi\right)-i \nabla \cdot\left(\frac{1}{\varepsilon} \mathbf{k} \phi\right)-i \frac{1}{\varepsilon} \mathbf{k} \cdot \nabla \phi+\frac{\|\mathbf{k}\|^{2}}{\varepsilon} \phi=\eta \phi, \tag{5}
\end{equation*}
$$

and for TM modes

$$
\begin{equation*}
-\nabla^{2} \phi-2 i \mathbf{k} \cdot \nabla \phi+\|\mathbf{k}\|^{2} \phi=\eta \varepsilon \phi, \tag{6}
\end{equation*}
$$

under the following periodicity conditions

$$
\begin{aligned}
\phi(x, 0) & =\phi(x, b), \quad \phi(0, y)=\phi(a, y) \\
\frac{\partial \phi}{\partial y}(x, 0) & =\frac{\partial \phi}{\partial y}(x, b), \quad \frac{\partial \phi}{\partial x}(0, y)=\frac{\partial \phi}{\partial x}(a, y) .
\end{aligned}
$$

## FDFD Method

Let us introduce the grid points

$$
\mathbf{x}_{j, l}=\left(\frac{j a}{n}, \frac{l b}{m}\right),
$$

where $j=0,1, \ldots, n, n+1$ and $I=0,1, \ldots, m, m+1$.
Then finite differencing Eq. (5) (TE modes) and Eq. (6) (TM modes) yields, for $h_{x}=a / n$ and $h_{y}=b / m$,

$$
\begin{align*}
& \frac{1}{2}\left(\frac{1}{\varepsilon_{j+1, l}}+\frac{1}{\varepsilon_{j, l}}\right)\left[-\frac{1}{h_{x}^{2}}-\frac{i k_{x}}{h_{x}}\right] \phi_{j+1, l}+\frac{1}{2}\left(\frac{1}{\varepsilon_{j, l}}+\frac{1}{\varepsilon_{j-1, l}}\right)\left[-\frac{1}{h_{x}^{2}}+\frac{i k_{x}}{h_{x}}\right] \phi_{j-1, l} \\
& +\frac{1}{2}\left(\frac{1}{\varepsilon_{j, l+1}}+\frac{1}{\varepsilon_{j, l}}\right)\left[-\frac{1}{k_{y}^{2}}-\frac{i k_{y}}{h_{y}}\right] \phi_{j, l+1}+\frac{1}{2}\left(\frac{1}{\varepsilon_{j, l}}+\frac{1}{\varepsilon_{j, l-1}}\right)\left[-\frac{1}{h_{y}^{2}}+\frac{i k_{y}}{h_{y}}\right] \phi_{j, l-1} \\
& +\left\{\frac{1}{4}\left(\frac{1}{\varepsilon_{j+1, l}}+\frac{2}{\varepsilon_{j, l}}+\frac{1}{\varepsilon_{j-1, l}}\right)\left[\frac{2}{h_{x}^{2}}+k_{x}^{2}\right]\right. \\
& \left.+\frac{1}{4}\left(\frac{1}{\varepsilon_{j, l+1}}+\frac{2}{\varepsilon_{j, l}}+\frac{1}{\varepsilon_{j, l-1}}\right)\left[\frac{2}{h_{y}^{2}}+k_{y}^{2}\right]\right\} \phi_{j, l}=\eta \phi_{j, l} \tag{7}
\end{align*}
$$

## FDFD Method

$$
\begin{align*}
& -\frac{\phi_{j+1, I}-2 \phi_{j, I}+\phi_{j-1, I}}{h_{x}^{2}}-\frac{\phi_{j, I+1}-2 \phi_{j, I}+\phi_{j, I-1}}{h_{y}^{2}} \\
& -2 i k_{x} \frac{\phi_{j+1, I}-\phi_{j-1, I}}{2 h_{x}}-2 i k_{y} \frac{\phi_{j, I+1}-\phi_{j, I-1}}{2 h_{y}}+\left[k_{x}^{2}+k_{y}^{2}\right] \phi_{j, l} \\
& =\eta \varepsilon_{j, I} \phi_{j, l} \tag{8}
\end{align*}
$$

Equations (8) and (17) can both be written in the form

$$
(C-\eta D) \Psi=0
$$

## Modi TE

- C nositive semidefinite sparse hermitian matrix;
- $D$ identity matrix of order $m n$.


## Modi TM

- C two-index sparse circulant matrix;
- D diagonal matrix with positive entries.


## FDFD Method

$$
\begin{align*}
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- $C$ two-index sparse circulant matrix;
- $D$ diagonal matrix with positive entries.


## FDFD Method

$$
C=\left(\begin{array}{cccc|cccc|cccc|cccc}
\alpha & \beta & 0 & \bar{\beta} & \gamma & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} & 0 & 0 & 0 \\
\bar{\beta} & \alpha & \beta & 0 & 0 & \gamma & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} & 0 & 0 \\
0 & \bar{\beta} & \alpha & \beta & 0 & 0 & \gamma & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} & 0 \\
\beta & 0 & \bar{\beta} & \alpha & 0 & 0 & 0 & \gamma & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} \\
\hline \bar{\gamma} & 0 & 0 & 0 & \alpha & \beta & 0 & \bar{\beta} & \gamma & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & \bar{\gamma} & 0 & 0 & \bar{\beta} & \alpha & \beta & 0 & 0 & \gamma & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & \bar{\gamma} & 0 & 0 & \bar{\beta} & \alpha & \beta & 0 & 0 & \gamma & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & \bar{\gamma} & \beta & 0 & \bar{\beta} & \alpha & 0 & 0 & 0 & \gamma & 0 & 0 & 0 & 0 \\
\hline 0 & 0 & 0 & 0 & \bar{\gamma} & 0 & 0 & 0 & \alpha & \beta & 0 & \bar{\beta} & \gamma & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & \bar{\gamma} & 0 & 0 & \bar{\beta} & \alpha & \beta & 0 & 0 & \gamma & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} & 0 & 0 & \bar{\beta} & \alpha & \beta & 0 & 0 & \gamma & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} & \beta & 0 & \bar{\beta} & \alpha & 0 & 0 & 0 & \gamma \\
\hline \gamma & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} & 0 & 0 & 0 & \alpha & \beta & 0 & \beta \\
0 & \gamma & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} & 0 & 0 & \bar{\beta} & \alpha & \beta & 0 \\
0 & 0 & \gamma & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} & 0 & 0 & \bar{\beta} & \alpha & \beta \\
0 & 0 & 0 & \gamma & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \bar{\gamma} & \beta & 0 & \bar{\beta} & \alpha
\end{array}\right),
$$

## FDFD Method

where

$$
\begin{gathered}
\alpha=\left(\frac{2}{h_{x}^{2}}+\frac{2}{h_{y}^{2}}+k^{2}\right), \\
\beta=\left(-\frac{1}{h_{x}^{2}}+i \frac{k_{x}}{h_{x}}\right), \quad \bar{\beta}=\left(-\frac{1}{h_{x}^{2}}-i \frac{k_{x}}{h_{x}}\right), \\
\gamma=\left(-\frac{1}{h_{y}^{2}}+i \frac{k_{y}}{h_{y}}\right), \quad \bar{\gamma}=\left(-\frac{1}{h_{y}^{2}}-i \frac{k_{y}}{h_{y}}\right) .
\end{gathered}
$$

The eigenvalues of $C$ are the numbers

$$
\begin{aligned}
\hat{c}(z, w ; \mathbf{k}) & =\frac{2}{h_{x}^{2}}+k_{x}^{2}+k_{y}^{2}+\left(-\frac{1}{h_{x}^{2}}+\frac{i k_{x}}{h_{x}}\right) z+\left(-\frac{1}{h_{x}^{2}}-\frac{i k_{x}}{h_{x}}\right) z^{-1} \\
& +\frac{2}{h_{y}^{2}}+\left(-\frac{1}{h^{2}}+\frac{i k_{y}}{h_{y}}\right) w+\left(-\frac{1}{h_{y}^{2}}-\frac{i k_{y}}{h_{y}}\right) w^{-1}
\end{aligned}
$$

where $z^{n}=1$ and $w^{m}=1$.

## FDFD Method

Writing $z=e^{i \theta_{j}}$ with $\theta_{j}=\frac{2 \pi j}{n}$ and $w=e^{i \varphi_{l}}$ with $\varphi_{l}=\frac{2 \pi l}{m}$, we can write the eigenvalues in the form

$$
\hat{c}(z, w ; \mathbf{k})=k_{x}^{2}+k_{y}^{2}+\frac{2}{h_{x}^{2}}\left(1-\cos \theta_{j}\right)-\frac{2 k_{x}}{h_{x}} \sin \theta_{j}+\frac{2}{h_{y}^{2}}\left(1-\cos \varphi_{I}\right)-\frac{2 k_{y}}{h_{y}} \sin \varphi_{I},
$$

where $j=0,1, \ldots, n-1$ and $I=0,1, \ldots, m-1$.

$$
\begin{aligned}
E_{\mathrm{abs}}= & -\frac{1}{3}\left(\frac{\pi j}{n}\right)^{2}\left[\left(\frac{2 \pi j}{a}+k_{x}\right)^{2}-k_{x}^{2}\right]\left\{1+O\left(\left(\frac{j}{n}\right)^{2}\right)\right\} \\
& -\frac{1}{3}\left(\frac{\pi I}{m}\right)^{2}\left[\left(\frac{2 \pi l}{b}+k_{y}\right)^{2}-k_{y}^{2}\right]\left\{1+O\left(\left(\frac{l}{m}\right)^{2}\right)\right\}
\end{aligned}
$$

For the relative error we then get the following upper bound:

$$
E_{\mathrm{rel}}=\max \left[\frac{1}{3}\left(\frac{\pi j}{n}\right)^{2}\left\{1+O\left(\left(\frac{j}{n}\right)^{2}\right)\right\}, \frac{1}{3}\left(\frac{\pi I}{m}\right)^{2}\left\{1+O\left(\left(\frac{l}{m}\right)^{2}\right)\right\}\right] .
$$

## FDFE Method

Putting $\mathbf{A}=\left\{t_{1} \mathbf{a}_{1}+t_{2} \mathbf{a}_{2}: 0 \leq t_{1}, t_{2}<1\right\}$, we define the complex Hilbert spaces $H_{\text {per }}$ and $H_{\text {per }}^{1}$ consisting of those measurable complex-valued functions $\phi$ on $\mathbb{R}^{2}$ which satisfy the periodicity condition $\phi\left(\mathbf{x}+m_{1} \mathbf{a}_{1}+m_{2} \mathbf{a}_{2}, \mathbf{k}\right)=\phi(\mathbf{x}, \mathbf{k})$ and are finite with respect to the following respective squared norms:

$$
\begin{aligned}
& \|\phi\|_{H_{\mathrm{per}}}^{2}=\iint_{\mathbf{A}} d x d y|\phi(x, y)|^{2} \\
& \|\phi\|_{H_{\text {per }}^{1}}^{2}=\iint_{\mathbf{A}} d x d y\left(|\phi(x, y)|^{2}+\|\nabla \phi(x, y)\|^{2}\right)
\end{aligned}
$$

As a consequence of the first Green identity and the periodicity condition, we see that $\phi \in H_{\text {per }}^{1}$ is a variational solution to (6) (TM mode) if


## FDFE Method

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\end{aligned}
$$

As a consequence of the first Green identity and the periodicity condition, we see that $\phi \in H_{\text {per }}^{1}$ is a variational solution to (6) (TM mode) if

$$
\begin{equation*}
\iint_{\mathbf{A}} d x d y\left\{\nabla \phi \cdot \nabla v^{*}-2 i[\mathbf{k} \cdot \nabla \phi] v^{*}+\|\mathbf{k}\|^{2} \phi v^{*}-\eta \varepsilon \phi v^{*}\right\}=0, \tag{9}
\end{equation*}
$$

for every $v \in H_{\text {per }}^{1}$.

## FDFE Method

Analogously, we call $\phi \in H_{\text {per }}^{1}$ a distributional solution to (5) (TE mode) if

$$
\iint_{\mathbf{A}} d x d y\left\{\frac{1}{\varepsilon} \nabla \phi \cdot \nabla v^{*}-i v^{*} \mathbf{k} \cdot \nabla\left(\frac{1}{\varepsilon} \phi\right)-\frac{i}{\varepsilon} v^{*} \mathbf{k} \cdot \nabla \phi+\frac{\|\mathbf{k}\|^{2}}{\varepsilon} \phi v^{*}-\eta \phi v^{*}\right\}=0,
$$ for every $v \in H_{\text {per }}^{1}$. Putting $h_{x}=(a / n), h_{y}=(b / m)$, we introduce the bivariate functions


extended periodically to $(x, y) \in \mathbb{R}^{2}$. Here, for $(j, I) \in \mathbb{Z}^{2}$, we have $x_{j}=j_{1} h_{1}=\left(j_{1} / n\right) a_{1}$ and $y_{l}=j_{2} h_{2}=\left(j_{2} / m\right) a_{2}$ and we interpolate $\phi \in H_{\text {per }}^{1}$ as follows:


## FDFE Method

Analogously, we call $\phi \in H_{\text {per }}^{1}$ a distributional solution to (5) (TE mode) if

$$
\begin{equation*}
\iint_{\mathbf{A}} d x d y\left\{\frac{1}{\varepsilon} \nabla \phi \cdot \nabla v^{*}-i v^{*} \mathbf{k} \cdot \nabla\left(\frac{1}{\varepsilon} \phi\right)-\frac{i}{\varepsilon} v^{*} \mathbf{k} \cdot \nabla \phi+\frac{\|\mathbf{k}\|^{2}}{\varepsilon} \phi v^{*}-\eta \phi v^{*}\right\}=0 \tag{10}
\end{equation*}
$$

for every $v \in H_{\text {per }}^{1}$. Putting $h_{x}=(a / n), h_{y}=(b / m)$, we introduce the bivariate functions

$$
\varphi_{\left(j_{1}, j_{2}\right)}(x, y)=\left(1-\frac{\left|x-x_{j_{1} \mid}\right|}{h_{1}}\right)\left(1-\frac{\left|y-y_{j_{2}}\right|}{h_{2}}\right), \quad\left(j_{1}, j_{2}\right) \in \mathbb{Z}^{2}
$$

extended periodically to $(x, y) \in \mathbb{R}^{2}$. Here, for $(j, I) \in \mathbb{Z}^{2}$, we have $x_{j}=j_{1} h_{1}=\left(j_{1} / n\right) a_{1}$ and $y_{l}=j_{2} h_{2}=\left(j_{2} / m\right) a_{2}$ and we interpolate $\phi \in H_{\text {per }}^{1}$ as follows:

$$
\phi(x, y)=\sum_{j_{1}=0}^{n-1} \sum_{j_{2}=0}^{m-1} \phi_{\left(j_{1}, j_{2}\right)} \varphi_{\left(j_{1}, j_{2}\right)}(x, y)
$$

and take $v=\varphi_{\left(1_{1}, l_{2}\right)}$ for every $I_{1} \in\{0,1, \ldots, n-1\}$ and $I_{2} \in\{0,1, \ldots, m-1\}$.

## FDFE Method

Bivariate functions

$$
\varphi_{\left(j_{1}, j_{2}\right)}(x, y)=\left(1-\frac{\mid x-x_{j_{1} \mid}}{h_{1}}\right)\left(1-\frac{\left|y-y_{j_{2} \mid}\right|}{h_{2}}\right), \quad\left(j_{1}, j_{2}\right) \in \mathbb{Z}^{2},
$$

and their support:


## FDFE Method

We obtain the linear system (TM mode) of order nm

$$
\begin{align*}
\sum_{j^{\prime}=0}^{n-1} \sum_{l^{\prime}=0}^{m-1} \phi_{\left(j^{\prime}, l^{\prime}\right)} & \int_{0}^{a} d x \int_{0}^{b} d y\left\{\left(\nabla \varphi_{\left(j^{\prime}, l^{\prime}\right)}+i \varphi_{\left(j^{\prime}, l^{\prime}\right)} \mathbf{k}\right) \cdot\left(\nabla \varphi_{(j, l)}-i \varphi_{(j, /)} \mathbf{k}\right)\right\} \\
& =\eta \sum_{j^{\prime}=0}^{n-1} \sum_{l^{\prime}=0}^{m-1} \phi_{\left(j^{\prime}, l^{\prime}\right)} \int_{0}^{a} d x \int_{0}^{b} d y \varepsilon(x, y) \varphi_{\left(j^{\prime}, l^{\prime}\right)}(x, y) \varphi_{(j, l)}(x, y) \tag{11}
\end{align*}
$$

whose unknowns are the values of $\phi(x, y)$ at the interpolation points of the photonic cell $0 \leq x \leq a, 0 \leq x \leq b$. From (10) (TE mode) we obtain instead

$$
\begin{align*}
\sum_{j^{\prime}=0}^{n-1} \sum_{l^{\prime}=0}^{m-1} \phi_{\left(j^{\prime}, l^{\prime}\right)} & \int_{0}^{a} \int_{0}^{b} \frac{d x d y}{\varepsilon(x, y)}\left\{\left(\nabla \varphi_{\left(j^{\prime}, l^{\prime}\right)}+i \varphi_{\left(j^{\prime}, l^{\prime}\right)} \mathbf{k}\right) \cdot\left(\nabla \varphi_{(j, l)}-i \varphi_{(j, l)} \mathbf{k}\right)\right\} \\
= & \eta \sum_{j^{\prime}=0}^{n-1} \sum_{l^{\prime}=0}^{m-1} \phi_{\left(j^{\prime}, l^{\prime}\right)} \int_{0}^{a} d x \int_{0}^{b} d y \varphi_{\left(j^{\prime}, l^{\prime}\right)}(x, y) \varphi_{(j, l)}(x, y) \tag{12}
\end{align*}
$$

## FDFE Method

The linear systems (11) and (12) constitute the finite element schemes to compute the eigenvalues $\eta$ for fixed wavevector $\mathbf{k}$ for the TM and TE modes, respectively.

$$
A=\left(\begin{array}{cccc|cccc|cccc|cccc}
\alpha & \beta_{2} & 0 & \bar{\beta}_{2} & \beta_{1} & \gamma_{1} & 0 & \gamma_{2} & 0 & 0 & 0 & 0 & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\gamma}_{1} \\
\bar{\beta}_{2} & \alpha & \beta_{2} & 0 & \gamma_{2} & \beta_{1} & \gamma_{1} & 0 & 0 & 0 & 0 & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 \\
0 & \bar{\beta}_{2} & \alpha & \beta_{2} & 0 & \gamma_{2} & \beta_{1} & \gamma_{1} & 0 & 0 & 0 & 0 & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \bar{\gamma}_{2} \\
\beta_{2} & 0 & \bar{\beta}_{2} & \alpha & \gamma_{1} & 0 & \gamma_{2} & \beta_{1} & 0 & 0 & 0 & 0 & \bar{\gamma}_{2} & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} \\
\hline \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\gamma}_{1} & \alpha & \beta_{2} & 0 & \bar{\beta}_{2} & \beta_{1} & \gamma_{1} & 0 & \gamma_{2} & 0 & 0 & 0 & 0 \\
\bar{\gamma}_{1} & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\beta}_{2} & \alpha & \beta_{2} & 0 & \gamma_{2} & \beta_{1} & \gamma_{1} & 0 & 0 & 0 & 0 & 0 \\
0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\beta}_{2} & \alpha & \beta_{2} & 0 & \gamma_{2} & \beta_{1} & \gamma_{1} & 0 & 0 & 0 & 0 \\
\bar{\gamma}_{2} & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \beta_{2} & 0 & \bar{\beta}_{2} & \alpha & \gamma_{1} & 0 & \gamma_{2} & \beta_{1} & 0 & 0 & 0 & 0 \\
\hline 0 & 0 & 0 & 0 & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\gamma}_{1} & \alpha & \beta_{2} & 0 & \bar{\beta}_{2} & \beta_{1} & \gamma_{1} & 0 & \gamma_{2} \\
0 & 0 & 0 & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\beta}_{2} & \alpha & \beta_{2} & 0 & \gamma_{2} & \beta_{1} & \gamma_{1} & 0 \\
0 & 0 & 0 & 0 & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\beta}_{2} & \alpha & \beta_{2} & 0 & \gamma_{2} & \beta_{1} & \gamma_{1} \\
0 & 0 & 0 & 0 & \bar{\gamma}_{2} & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \beta_{2} & 0 & \bar{\beta}_{2} & \alpha & \gamma_{1} & 0 & \gamma_{2} & \beta_{1} \\
\hline \beta_{1} & \gamma_{1} & 0 & \gamma_{2} & 0 & 0 & 0 & 0 & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\gamma}_{1} & \alpha & \beta_{2} & 0 & \bar{\beta}_{2} \\
\gamma_{2} & \beta_{1} & \gamma_{1} & 0 & 0 & 0 & 0 & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\beta}_{2} & \alpha & \beta_{2} & 0 \\
0 & \gamma_{2} & \beta_{1} & \gamma_{1} & 0 & 0 & 0 & 0 & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \bar{\gamma}_{2} & 0 & \bar{\beta}_{2} & \alpha & \beta_{2} \\
\gamma_{1} & 0 & \gamma_{2} & \beta_{1} & 0 & 0 & 0 & 0 & \bar{\gamma}_{2} & 0 & \bar{\gamma}_{1} & \bar{\beta}_{1} & \beta_{2} & 0 & \bar{\beta}_{2} & \alpha
\end{array}\right)
$$

## FDFE Method

$$
\begin{aligned}
& \text { where } \\
& \alpha=\frac{4}{3} \frac{h_{y}}{h_{x}}+\frac{4}{3} \frac{h_{x}}{h_{y}}+k^{2} \frac{4}{9} h_{x} h_{y}, \\
& \beta_{1}=-\frac{1}{3}+k^{2} \frac{1}{9} h_{x} h_{y}-i k_{y} \frac{2}{3} h_{x}, \quad \bar{\beta}_{1}=-\frac{1}{3}+k^{2} \frac{1}{9} h_{x} h_{y}+i k_{y} \frac{2}{3} h_{x} \text {, } \\
& \beta_{2}=-\frac{1}{3}+k^{2} \frac{1}{9} h_{x} h_{y}-i k_{x} \frac{2}{3} h_{y}, \quad \bar{\beta}_{2}=-\frac{1}{3}+k^{2} \frac{1}{9} h_{x} h_{y}+i k_{x} \frac{2}{3} h_{y}, \\
& \gamma_{1}=-\frac{1}{3}+k^{2} \frac{1}{36} h_{x} h_{y}-i \frac{k_{x} h_{y}+k_{y} h_{x}}{6}, \quad \bar{\gamma}_{1}=-\frac{1}{3}+k^{2} \frac{1}{36} h_{x} h_{y}+i \frac{k_{x} h_{y}+k_{y} h_{x}}{6} \text {, } \\
& \gamma_{2}=-\frac{1}{3}+k^{2} \frac{1}{36} h_{x} h_{y}+i \frac{k_{x} h_{y}-k_{y} h_{x}}{6}, \quad \bar{\gamma}_{2}=-\frac{1}{3}+k^{2} \frac{1}{36} h_{x} h_{y}-i \frac{k_{x} h_{y}-k_{y} h_{x}}{6} . \\
& B=\left(\begin{array}{llll|llll|llll|llll}
a & b & 0 & b & b & c & 0 & c & 0 & 0 & 0 & 0 & b & c & 0 & c \\
b & a & b & 0 & c & b & c & 0 & 0 & 0 & 0 & 0 & c & b & c & 0 \\
0 & b & a & b & 0 & c & b & c & 0 & 0 & 0 & 0 & 0 & c & b & c \\
b & 0 & b & a & c & 0 & c & b & 0 & 0 & 0 & 0 & c & 0 & c & b \\
\hline b & c & 0 & c & a & b & 0 & b & b & c & 0 & c & 0 & 0 & 0 & 0 \\
c & b & c & 0 & b & a & b & 0 & c & b & c & 0 & 0 & 0 & 0 & 0 \\
0 & c & b & c & 0 & b & a & b & 0 & c & b & c & 0 & 0 & 0 & 0 \\
c & 0 & c & b & b & 0 & b & a & c & 0 & c & b & 0 & 0 & 0 & 0 \\
\hline 0 & 0 & 0 & 0 & b & c & 0 & c & a & b & 0 & b & b & c & 0 & c \\
0 & 0 & 0 & 0 & c & b & c & 0 & b & a & b & 0 & c & b & c & 0 \\
0 & 0 & 0 & 0 & 0 & c & b & c & 0 & b & a & b & 0 & c & b & c \\
0 & 0 & 0 & 0 & c & 0 & c & b & b & 0 & b & a & c & 0 & c & b \\
\hline b & c & 0 & c & 0 & 0 & 0 & 0 & b & c & 0 & c & a & b & 0 & b \\
c & b & c & 0 & 0 & 0 & 0 & 0 & c & b & c & 0 & b & a & b & 0 \\
0 & c & b & c & 0 & 0 & 0 & 0 & 0 & c & b & c & 0 & b & a & b \\
c & 0 & c & b & 0 & 0 & 0 & 0 & c & 0 & c & b & b & 0 & b & a
\end{array}\right),
\end{aligned}
$$

where

$$
a=\frac{4}{9} h_{x} h_{y}, \quad b=\frac{1}{9} h_{x} h_{y}, \quad c=\frac{1}{36} h_{x} h_{y}
$$

## FDFE Method

Eigenvalues in the homogenous case $(\varepsilon(x, y)=1)$

$$
\eta(\mathbf{k})=\frac{\hat{a}(z, w ; \mathbf{k})}{\hat{b}(z, w ; \mathbf{k})},
$$

where

$$
\begin{aligned}
& \hat{a}(z, w ; \mathbf{k})=a\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}, j_{2}\right)}\right)+a\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}+1, j_{2}\right)}\right) z+\bar{a}\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}+1, j_{2}\right)}\right) z^{-1} \\
& +a\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}, j_{2}+1\right)}\right) w+\bar{a}\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}, j_{2}+1\right)}\right) w^{-1}, \\
& \hat{b}(z, w ; \mathbf{k})=b\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}, j_{2}\right)}\right)+b\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}+1, j_{2}\right)}\right) z+\bar{b}\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}+1, j_{2}\right)}\right) z^{-1} \\
& +b\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}, j_{2}+1\right)}\right) w+\bar{b}\left(\phi_{\left(j_{1}, j_{2}\right)}, \phi_{\left(j_{1}, j_{2}+1\right)}\right) w^{-1},
\end{aligned}
$$

with $z^{n}=1$ and $w^{m}=1$.

## FDFE Method

As in the FDFD method we can easily prove that:

$$
\left.\left.\begin{array}{rl}
E_{\mathrm{abs}}= & \operatorname{const}_{1}
\end{array}\right]\left(\frac{2 \pi j}{a}+k_{x}\right)^{2}-k_{x}^{2}\right]\left\{1+O\left(\left(\frac{j}{n}\right)^{2}\right)\right\}+,
$$

and for the relative error we then get the following upper bound:

$$
E_{\text {rel }}=-\max \left[\operatorname{const}_{1}\left\{1+O\left(\left(\frac{j}{n}\right)^{2}\right)\right\}, \text { const }_{2}\left\{1+O\left(\left(\frac{l}{m}\right)^{2}\right)\right\}\right],
$$

$n$ and $m$ being the number of mesh points along the $x$ and $y$ axes, respectively.

## Numerical Results






## Numerical Results

In the nonrectangular 2D case we use the basis vectors $\mathbf{a}_{1}$ and $\mathbf{a}_{2}$ to convert the Helmholtz equation to cartesian coordinates and both FDFD and FDFE methods work successfully:


- Pietro Contu, C. van der Mee, and Sebastiano Seatzu. Fast and Effective Finite Difference Method for 2D Photonic Crystals, Communications in Applied and Industrial Mathematics (CAIM), (2011)
- Pietro Contu, C. van der Mee, and Sebastiano Seatzu. A Finite

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## FDFD method for 3D PC

Let us now introduce the $3 n_{1} n_{2} n_{3}$-dimensional (real or complex) vector space $\mathrm{H}_{n_{1}, n_{2}, n_{3}}$ of columns vectors indexed by
$\left(j_{1}, j_{2}, j_{3}, s\right) \in \mathbb{Z}\left[n_{1}\right] \times \mathbb{Z}\left[n_{2}\right] \times \mathbb{Z}\left[n_{3}\right] \times\{1,2,3\}$, where $\left(j_{1}, j_{2}, j_{3}\right)$ is a lower index and $s$ is an upper index.
We define the discrete divergence:

$$
\begin{aligned}
{[\nabla \cdot \mathbf{F}]_{j_{1}, j_{2}, j_{3}}=} & \frac{F_{j_{1}+1, j_{2}, j_{3}}^{1}-F_{j_{1}-1, j_{2}, j_{3}}^{1}}{2 h_{1}}+\frac{F_{j_{1}, j_{2}+1, j_{3}}^{2}-F_{j_{1}, j_{2}-1, j_{3}}^{2}}{2 h_{2}} \\
& +\frac{F_{j_{1}, j_{2}, j_{3}+1}^{3}-F_{j_{1}, j_{2}, j_{3}-1}^{3}}{2 h_{3}},
\end{aligned}
$$

and the discrete curl $\nabla \times: \mathrm{H}_{n_{1}, n_{2}, n_{2}} \rightarrow \mathrm{H}_{n_{1}, n_{2}, n_{3}}$ as follows:

$$
\begin{aligned}
& (\nabla \times \mathbf{F})_{j_{1}, j_{2}, j_{3}}^{1}=\left(\partial_{2} F^{3}-\partial_{3} F^{2}\right)_{j_{1}, j_{2}, j_{3}}, \\
& (\nabla \times \mathbf{F})_{j_{1}, j_{2}, j_{3}}=\left(\partial_{3} F^{1}-\partial_{1} F^{3}\right)_{j_{1}, j_{2}, j_{3}}, \\
& (\nabla \times \mathbf{F})_{j_{1}, j_{2}, j_{3}}=\left(\partial_{1} F^{2}-\partial_{2} F^{1}\right)_{j_{1}, j_{2}, j_{3}} .
\end{aligned}
$$

## FDFD Method for 3D PC

We have to solve the spectral problem under periodicity conditions:

$$
\begin{align*}
& \nabla \cdot[\varepsilon(\mathbf{x}) \mathcal{E}(\mathbf{x})]+i \mathbf{k} \cdot[\varepsilon(\mathbf{x}) \mathcal{E}(\mathbf{x})]=0  \tag{13}\\
& \nabla \times \mathcal{H}(\mathbf{x})+i[\mathbf{k} \times \mathcal{H}(\mathbf{x})]-i \sqrt{\eta} \varepsilon(\mathbf{x}) \mathcal{E}(\mathbf{x})=0  \tag{14}\\
& \nabla \times \mathcal{E}(\mathbf{x})+i[\mathbf{k} \times \mathcal{E}(\mathbf{x})]+i \sqrt{\eta} \varepsilon(\mathbf{x}) \mathcal{H}(\mathbf{x})=0  \tag{15}\\
& \nabla \cdot[\mathcal{H}(\mathbf{x})]+i \mathbf{k} \cdot \mathcal{H}(\mathbf{x})=0 \tag{16}
\end{align*}
$$

## Proposition

For $\sqrt{\eta}>0$, any solution to the equations (14) and (15) satisfies the
discrete divergence equations

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$$
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& \nabla \times \mathcal{E}(\mathbf{x})+i[\mathbf{k} \times \mathcal{E}(\mathbf{x})]+i \sqrt{\eta} \varepsilon(\mathbf{x}) \mathcal{H}(\mathbf{x})=0  \tag{15}\\
& \nabla \cdot[\mathcal{H}(\mathbf{x})]+i \mathbf{k} \cdot \mathcal{H}(\mathbf{x})=0 \tag{16}
\end{align*}
$$

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For $\sqrt{\eta}>0$, any solution to the equations (14) and (15) satisfies the discrete divergence equations

$$
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& \nabla \cdot[\mathcal{H}(\mathbf{x})]+i \mathbf{k} \cdot \mathcal{H}(\mathbf{x})=0
\end{aligned}
$$

## FDFD Method for 3D PC

Finite Differencing Eqs. (14) and (15) we get a linear system of order $6 n_{1} n_{2} n_{3} \times 6 n_{1} n_{2} n_{3}$, where $n_{1}, n_{2}$ and $n_{3}$ are the numbers of grid points along the $x, y$ and $z$ axes, respectively:

$$
\begin{aligned}
& \frac{1}{2 h_{2}}\left(H_{j_{1}, j_{2}+1, j_{3}}^{3}-H_{j_{1}, j_{2}-1, j_{3}}^{3}\right)-\frac{1}{2 h_{3}}\left(H_{j_{1}, j_{2}, j_{3}+1}^{2}-H_{j_{1}, j_{2}, j_{3}-1}^{2}\right)+i\left(k_{2} H_{j_{1}, j_{2}, j_{3}}^{3}-k_{3} H_{j_{1}, j_{2}, j_{3}}^{2}\right) \\
& =i \sqrt{\eta} \varepsilon_{j_{1}, j_{2}, j_{3}} E_{j_{1}, j_{2}, j_{3}}^{1}, \\
& \frac{1}{2 h_{3}}\left(H_{j_{1}, j_{2}, j_{3}+1}^{1}-H_{j_{1}, j_{2}, j_{3}-1}^{1}\right)-\frac{1}{2 h_{1}}\left(H_{j_{1}+1, j_{2}, j_{3}}^{3}-H_{j_{1}-1, j_{2}, j_{3}}^{3}\right)+i\left(k_{3} H_{j_{1}, j_{2}, j_{3}}^{1}-k_{1} H_{j_{1}, j_{2}, j_{3}}^{3}\right) \\
& =i \sqrt{\eta} \varepsilon_{j_{1}, j_{2}, j_{3}}^{3} E_{j_{1}, j_{2}, j_{3}}^{2}, \\
& \frac{1}{2 h_{1}}\left(H_{j_{1}+1, j_{2}, j_{3}}^{2}-H_{j_{1}-1, j_{2}, j_{3}}^{2}\right)-\frac{1}{2 h_{2}}\left(H_{j_{1}, j_{2}+1, j_{3}}^{1}-H_{j_{1}, j_{2}-1, j_{3}}^{1}\right)+i\left(k_{1} H_{j_{1}, j_{2}, j_{3}}^{2}-k_{2} H_{j_{1}, j_{2}, j_{3}}^{1}\right) \\
& =i \sqrt{\eta} \varepsilon_{j_{1}, j_{2}, j_{3}}^{3} E_{j_{1}, j_{2}, j_{3}}^{3}, \\
& \frac{1}{2 h_{2}}\left(E_{j_{1}, j_{2}+1, j_{3}}^{3}-E_{j_{1}, j_{2}-1, j_{3}}^{3}\right)-\frac{1}{2 h_{3}}\left(E_{j_{1}, j_{2}, j_{3}+1}^{2}-E_{j_{1}, j_{2}, j_{3}-1}^{2}\right)+i\left(k_{2} E_{j_{1}, j_{2}, j_{3}}^{3}-k_{3} E_{j_{1}, j_{2}, j_{3}}^{2}\right) \\
& =i \sqrt{\eta} H_{1_{1}, j_{2}, j_{3}}^{1}, \\
& \frac{1}{2 h_{3}}\left(E_{j_{1}, j_{2}, j_{3}+1}^{1}-E_{j_{1}, j_{2}, j_{3}-1}^{1}\right)-\frac{1}{2 h_{1}}\left(E_{j_{1}+1, j_{2}, j_{3}}^{3}-E_{j_{1}-1, j_{2}, j_{3}}^{3}\right)+i\left(k_{3} E_{j_{1}, j_{2}, j_{3}}^{1}-k_{1} E_{j_{1}, j_{2}, j_{3}}^{3}\right) \\
& =i \sqrt{\eta} H_{j_{1}, j_{2}, j_{3}}^{2}, \\
& \frac{1}{2 h_{1}}\left(E_{j_{1}+1, j_{2}, j_{3}}^{2}-E_{j_{1}-1, j_{2}, j_{3}}^{2}\right)-\frac{1}{2 h_{2}}\left(E_{j_{1}, j_{2}+1, j_{3}}^{1}-E_{j_{1}, j_{2}-1, j_{3}}^{1}\right)+i\left(k_{1} E_{j_{1}, j_{2}, j_{3}}^{2}-k_{2} E_{j_{1}, j_{2}, j_{3}, j_{3}}^{1},\right. \\
& i \sqrt{\eta} H_{3}^{3},
\end{aligned}
$$

## FDFD Method for 3D PC

The $6 n_{1} n_{2} n_{3} \times 6 n_{1} n_{2} n_{3}$ linear system can be written in a more compact form:

$$
\left(\begin{array}{cc}
\mathbf{C} & i \sqrt{\eta} \mathbf{I}  \tag{18}\\
-i \sqrt{\eta} \varepsilon & \mathbf{C}
\end{array}\right)\binom{\mathbf{E}}{\mathbf{H}}=0
$$

where $\varepsilon=\varepsilon \otimes \square_{3}$ is a diagonal matrix with positive entries and $\mathbf{C}$ is a block circulant matrix with $3 \times 3$ blocks:

$$
\begin{gathered}
C_{0,0,0}=\left(\begin{array}{ccc}
0 & -i k_{3} & i k_{2} \\
i k_{3} & 0 & -i k_{1} \\
-i k_{2} & i k_{1} & 0
\end{array}\right), C_{ \pm 1,0,0}=\left(\begin{array}{ccc}
0 & 0 & 0 \\
0 & 0 & \mp \frac{1}{2 h_{1}} \\
0 & \pm \frac{1}{2 h_{1}} & 0
\end{array}\right), \\
C_{0, \pm 1,0}=\left(\begin{array}{ccc}
0 & 0 & \pm \frac{1}{2 h_{2}} \\
0 & 0 & 0 \\
\mp \frac{1}{2 h_{2}} & 0 & 0
\end{array}\right), C_{0,0, \pm 1}=\left(\begin{array}{ccc}
0 & \mp \frac{1}{2 h_{3}} & 0 \\
\pm \frac{1}{2 h_{3}} & 0 & 0 \\
0 & 0 & 0
\end{array}\right) .
\end{gathered}
$$

## FDFD Method for 3D PC



## FDFD Method for 3D PC

Writing the two equations (18) in the form $\mathbf{C H}=i \sqrt{\eta} \mathbf{E}$ and $\mathbf{C E}=-i \sqrt{\eta} \mathbf{H}$, we get after one iteration

Eigenvalue problem for E
$\square \mathbf{C}^{2} \mathbf{E}=\eta \boldsymbol{\varepsilon} \mathbf{E}$

Eigenvalue problem for H

- $\mathbf{C} \frac{1}{\varepsilon} \mathbf{C} \mathbf{H}=\eta \mathbf{H}$



## Conclusions

－FDFD method for 3D photonic crystal is in progress；
－Generalized eigenvalue problems appear in the study of photonic devices in optoelectronics；
－Algorithms which study multi－index circulant＋diagonal eigenvalue problems，in particular for large matrix orders，have to be properly implemented．

## Conclusions

- FDFD method for 3D photonic crystal is in progress;
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## Frequency Domain Methods

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