

Can clouds of points generate numerical storms?

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Genova, 16th-17th February 2012

Introduction

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- **Data with noise**: Each point of \mathbb{X} represents a cloud of points (numerically equivalent to \mathbb{X}). Structures based on polynomials involving real data **lose** many of their **rigorous algebraic properties**.

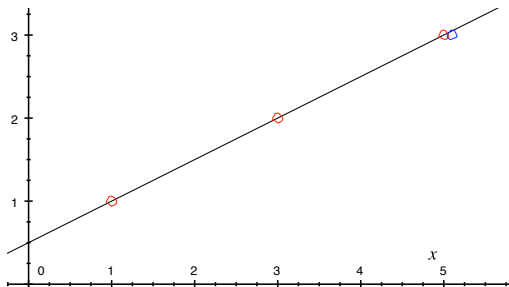
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Example Let $\mathbb{X} = \{(1, 1), (3, 2), (5, 3)\}$ and $\hat{\mathbb{X}} = \{(1, 1), (3, 2), (5.1, 3)\}$

$$\mathcal{I}(\mathbb{X}) : \begin{cases} x - 2y + 1 \\ y^3 - 6y^2 + 11y - 6 \end{cases} \quad \mathcal{I}(\hat{\mathbb{X}}) : \begin{cases} x^2 - 20x + 37y - 18 \\ xy - 43x + 81y - 39 \\ y^2 - 90.1x + 172.2y - 83.1 \end{cases}$$



Given a set \mathbb{X} of points we can compute the τ -Gröbner basis of $\mathcal{I}(\mathbb{X})$

The **Buchberger-Möller algorithm**

Input: A set of points \mathbb{X}

Output: A Gröbner basis of $\mathcal{I}(\mathbb{X})$

- **Step Zero:** $\mathcal{O} = \{1\}$
- **Generic Step:** $\mathcal{O} = \{t_1, \dots, t_k\}$ and $t >_{\tau} t_i$.
 $t(\mathbb{X}), t_1(\mathbb{X}), \dots, t_k(\mathbb{X})$ linearly dependent? (*)
Yes: polynomial of basis formed
No: t is added to \mathcal{O}

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- (*) \Leftrightarrow
- construct $M_{\mathcal{O}}(\mathbb{X}) = (t_1(\mathbb{X}), \dots, t_k(\mathbb{X}))$
 - solve LSP: $M_{\mathcal{O}}(\mathbb{X})\alpha(\mathbb{X}) = t(\mathbb{X})$
 - check whether $\rho(\mathbb{X}) = t(\mathbb{X}) - M_{\mathcal{O}}(\mathbb{X})\alpha(\mathbb{X}) = 0$

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Consider $\mathcal{O} = \{t_1 = 1, t_2 = y\} \quad t = x$

$$[t_1(\mathbb{X}), t_2(\mathbb{X}), t(\mathbb{X})] = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5 \end{bmatrix}$$

$$t(\mathbb{X}) - 2t_2(\mathbb{X}) + t_1(\mathbb{X}) = 0$$

$$[t_1(\hat{\mathbb{X}}), t_2(\hat{\mathbb{X}}), t(\hat{\mathbb{X}})] = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5.1 \end{bmatrix}$$

Independent vectors

Empirical points

Noisy data set \iff Empirical points: $\mathbb{X} \subset \mathbb{R}^n$ and a **tolerance** $\varepsilon \in \mathbb{R}^+$

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A generic \tilde{p} can be expressed as $\tilde{p} = (p_1 + e_1, \dots, p_n + e_n) \implies$
we make use of **error variables**

$$\mathbf{e} = (e_{11}, \dots, e_{s1}, e_{12}, \dots, e_{s2}, \dots, e_{1n}, \dots, e_{sn}) \text{ and } \|\mathbf{e}\|_{\infty} \leq \varepsilon$$

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A generic **admissible perturbation** $\tilde{\mathbb{X}}$ of \mathbb{X} is expressed as

$$\tilde{\mathbb{X}} = \mathbb{X}(\mathbf{e}) = \{p_1(\mathbf{e}), \dots, p_s(\mathbf{e})\}$$

Problem

Given a set \mathbb{X} of empirical points
determine a polynomial of **low degree** and the corresponding (simple)
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Given $\mathbb{X} = \{p_1, \dots, p_s\} \subseteq \mathbb{R}^n$ set of points, $\varepsilon \in \mathbb{R}^+$ tolerance
compute

$$\begin{aligned} f^* \in \mathbb{R}[x_1, \dots, x_n] \\ \mathbb{X}^* = \{p_1^*, \dots, p_s^*\} \subseteq \mathbb{R}^n \end{aligned} \quad \text{s.t.} \quad \begin{cases} f^*(p_i^*) = 0 \\ \|p_i^* - p_i\|_\infty < \varepsilon \end{cases} \quad \forall p_i^* \in \mathbb{X}^*$$

The **simplicity** of the model judged by the degree of f^*

The **goodness** of model by the max distance of \mathbb{X}^* from \mathbb{X}

Adapting the BM Algorithm to the empirical case

The New algorithm (empirical case)

Input: set of empirical points \mathbb{X} and tolerance ε

Out: low degree polynomial f vanishing at $\mathbb{X}(\hat{\mathbf{e}})$, $\|\hat{\mathbf{e}}\| < \varepsilon$

- **Generic Step:** $\mathcal{O} = \{t_1, \dots, t_k\}$ and $t >_{\tau} t_i$.
check whether there exists $\hat{\mathbf{e}}$ s.t. $\mathbb{X}(\hat{\mathbf{e}})$ is adm.pert. of \mathbb{X} and

$$\rho(\mathbb{X}(\hat{\mathbf{e}})) = t(\mathbb{X}(\hat{\mathbf{e}})) - M_{\mathcal{O}}(\mathbb{X}(\hat{\mathbf{e}}))\alpha(\mathbb{X}(\hat{\mathbf{e}})) = 0 \quad (*)$$

(Exact Case $\rho = t(\mathbb{X}) - M_{\mathcal{O}}(\mathbb{X})\alpha(\mathbb{X}) = 0$)

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$$(*) \quad \rho(\mathbf{e}) = 0 \quad \text{in} \quad D = \{\mathbf{e} : \|\mathbf{e}\|_{\infty} < \varepsilon, M_{\mathcal{O}}(\mathbf{e}) \text{ is full rank}\}$$

Underdetermined nonlinear systems

Problem: compute a solution of $\rho(\mathbf{e}) = 0$ s.t. $\mathbf{e} \in D$

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- **Normal Flow Algorithm.**¹ Let $\bar{\mathbf{x}} = \mathbf{0} \in D$, $\omega \ll 1$, $\mathbf{h} = (1, \dots, 1)$
 - While $\|\mathbf{h}\|_2 > \omega$ do
 - $\mathbf{h} = -\text{Jac}_\rho(\bar{\mathbf{x}})^\dagger \rho(\bar{\mathbf{x}})$
 - $\bar{\mathbf{x}} = \bar{\mathbf{x}} + \mathbf{h}$
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The NF Algorithm depends on the **conditioning** of $\text{Jac}_\rho(\bar{x})$

SO we adopt the following strategy:

- If $\text{Jac}_\rho(x)$ **well-conditioned** \Rightarrow we apply the NF Algorithm to ρ
- If $\text{Jac}_\rho(x)$ **ill-conditioned** \Rightarrow we construct $\hat{\rho} : D \rightarrow \mathbb{R}^m$ such that $\text{Jac}_{\hat{\rho}}(x)$ **well-conditioned** in D and $\|\hat{\rho}(x) - \rho(x)\|$ **small** in D

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Numerical Rank and Rank Revealing Decomposition

Our strategy is based on

- **Numerical Rank.** Let $A \in \text{Mat}_{m \times n}(\mathbb{R})$, $\delta > 0$ and $k > 1$. If

$$\sigma_1(A) \geq \dots \geq \sigma_r(A) > k\delta > \delta > \sigma_{r+1}(A) \geq \dots \geq \sigma_n(A)$$

then r is called the **numerical (δ, k) -rank** of A .

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- **Rank Revealing Decomposition**². Let $A \in \text{Mat}_{m \times n}(\mathbb{R})$ and $r = \text{numerical } (\delta, k)\text{-rank of } A \Rightarrow \exists$ a permutation matrix Π s.t.

$$A\Pi = Q \begin{pmatrix} R_{11} & R_{12} \\ 0 & R_{22} \end{pmatrix}$$

$$\sigma_{\min}(R_{11}) \geq \frac{k}{q(n,r)}\delta \quad \text{and} \quad \|R_{22}\|_2 \leq q(n,r)\delta$$

The first r columns of $A\Pi$ are strongly independent

²Hong, Pan (1992)

Back to the problem

We consider, at the first step of the Normal Flow Algorithm, the ill conditioned system

$$\mathbf{Jac}_\rho(0)h = -\rho(0)$$

We select the maximum number of “strongly independent equations”

- computing $r = \text{rank}_{\delta,k}(\mathbf{Jac}_\rho(0) \mid \rho(0))$, with $\delta \geq \varepsilon$;
- computing the Rank Revealing Decomposition of

$$\begin{pmatrix} \mathbf{Jac}_\rho(0)^t \\ \rho(0)^t \end{pmatrix} \Pi = Q \begin{pmatrix} R_{11} & R_{12} \\ 0 & R_{22} \end{pmatrix}$$

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$$\hat{\rho}(\mathbf{e}) = \begin{pmatrix} \Pi_1^t \rho(\mathbf{e}) \\ G \Pi_1^t \rho(\mathbf{e}) \end{pmatrix} \quad \text{where} \quad G = R_{12}^t R_{11}^{-t}$$

$$\widehat{\rho}(\mathbf{e}) = \left\{ \begin{array}{l} \Pi_1^t \rho(\mathbf{e}) = 0 \\ G \Pi_1^t \rho(\mathbf{e}) = 0 \end{array} \right. \begin{array}{l} \} r \\ \} m - r \end{array}$$

- the $m - r$ last equations depend on the first r equations;
- the first r rows of $\text{Jac}_{\widehat{\rho}}(0)$ (or of $\text{Jac}_{\widehat{\rho}}(\mathbf{e})$ if $\mathbf{e} \approx \mathbf{0}$) is well conditioned;
- $\|\widehat{\rho}(\mathbf{e}) - \Pi^t \rho(\mathbf{e})\|_2 \leq q(m, r)\delta + O(\delta^2) \quad \forall \mathbf{e} \in D$
If $\rho(\mathbf{e}^*) = 0$, $\mathbf{e}^* \in D$, then $\|\widehat{\rho}(\mathbf{e}) - \Pi^t \rho(\mathbf{e})\|_2 = O(\delta^2)$

Conclusion: we apply the NF algorithm to $\Pi_1^t \rho(\mathbf{e})$ which is

- equivalent to $\widehat{\rho}(\mathbf{e})$
- “close” to $\rho(\mathbf{e})$
- with **well-conditioned** Jacobian matrices on D .

Example

We consider the set of points created by perturbing less than 0.1 the coords of 6 points on $y^2 - x - 2y + 2 = 0$:

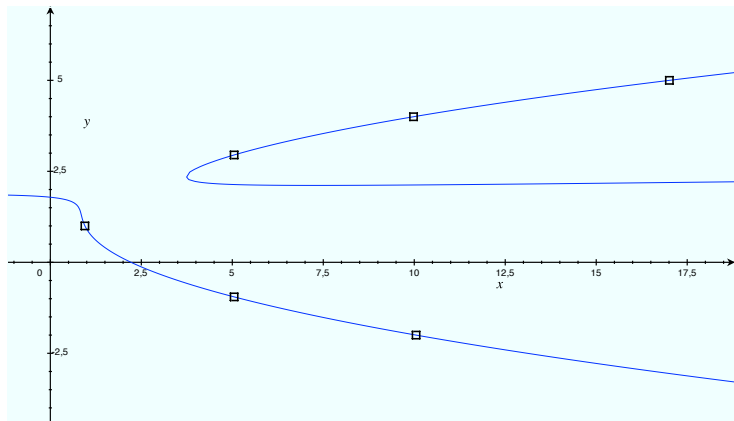
$$\mathbb{X} = \{(0.95, 1), (5.05, 2.95), (5.05, -0.95), (9.98, 4), (10.05, -2), (17.01, 5)\}$$

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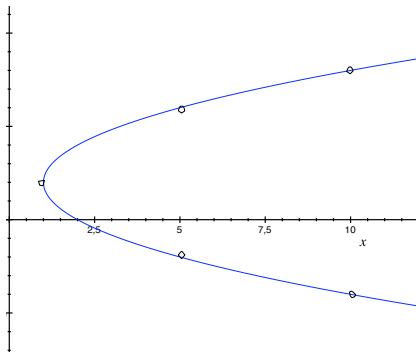
A straightforward computation using **BM algorithm** gives



Example

Our Algorithm applied to \mathbb{X} with $\varepsilon = 0.1$, $\delta = 2\varepsilon$, $k = 2$ computes

$$\bar{f} = y^2 - 0.9816x - 2.0176y + 1.9660 \quad (\approx y^2 - x - 2y + 2)$$

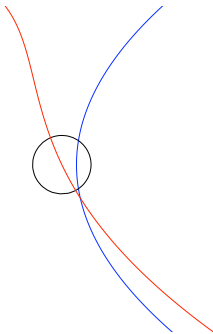


Singular values and condition number of $[\text{Jac}_\rho(0) \mid \rho(0)]$

$$\{6.39, 4.67, 3.33, 0.035, 0.02, 0.00\} \quad K_2(\text{Jac}_\rho(0) \mid \rho(0)) \approx 310$$

Example

Zooming around the first point we get...



Problem 1: Parameters

Empirical points \iff tolerance ε on the coordinates of the input points.

Numerical rank of $[\text{Jac}_\rho(0)|\rho(0)]$ \iff parameters δ and k s.t.

$$\sigma_1 \geq \dots \sigma_r > k\delta > \delta \geq \sigma_{r+1} \geq \sigma_m$$

What is the best choice of δ and k as function of ε ?

Problem 2: Strategy

A different strategy for solving the non linear system $\rho(\mathbf{e}) = 0$ avoiding the “almost dependent” equations (using the information about the tolerance...)