Genova, March 17, 2023

#### Genova ricorda Lawvere

#### Lawvere metric spaces in Weighted Algebraic Topology

Marco Grandis

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Lawvere generalised metric space [Lw] (1973), or  $\delta$ -space: - a set X equipped with a  $\delta$ -metric:  $\delta: X \times X \to [0, \infty]$ 

$$\delta(x,x) = 0, \qquad \delta(x,y) + \delta(y,z) \ge \delta(x,z)$$

(notation and terminology as in [Gr], Chapter 5).

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 $\delta$ **Mtr**: the category of  $\delta$ -spaces and weak contractions

 $f: X \to Y, \qquad \delta(x, x') \ge \delta(f(x), f(x'))$ 

- symmetric monoidal closed:

 $X \otimes Y$ ,  $\delta((x, y), (x', y')) = \delta(x, x') + \delta(y, y')$ . [-, -]: Lipschitz maps with the  $\delta$ -metric of uniform convergence.

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 $\delta_{\infty}$ **Mtr** : the larger category of  $\delta$ -spaces and Lipschitz maps:  $L\delta(x, x') \ge \delta(f(x), f(x'))$  (some  $L \ge 0$ ).

1. allowing  $\infty$ :  $\rightarrow \delta$ **Mtr** is complete and cocomplete (a product has the  $l_{\infty}$ -metric, by sup)

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3. The associated symmetric  $\delta$ -metric (and topology):

 $\begin{array}{l} : \ \delta \mathbf{Mtr} \to \mathbf{Mtr} \ (\text{the reflector}): \\ ! \delta(x, x') = \inf_{\mathbf{x}} \left( \sum_{j} \left( \delta(x_{j-1}, x_{j}) \land \delta(x_{j}, x_{j-1}) \right) \right) \\ \mathbf{x} = (x_{0}, ..., x_{p}), \quad x_{0} = x, \quad x_{p} = x', \end{array}$ 

greatest symmetric  $\delta$ -metric  $\leq \delta$ .

2. Some models and their directed structure The standard  $\delta$ -line  $\delta \mathbb{R}$ :  $\delta(x, y) = y - x$  if  $x \leq y$ , OR  $\infty$ 

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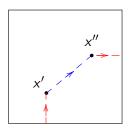
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 $\delta \mathbb{S}^2$ 

 $\delta(x', x''), \quad \delta(x'', x')$ 

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a path a:  $[0,1] \rightarrow X$  in a  $\delta$ -space has a *length*, or cost:  $\begin{aligned} \mathcal{L}(a) &= \sup_{\mathbf{t}} \mathcal{L}_{\mathbf{t}}(a) \in [0,\infty], \\ \mathcal{L}_{\mathbf{t}}(a) &= \sum \delta(a(t_{j-1}), a(t_{j})) \quad (\mathbf{t} : 0 = t_{0} < t_{1} < ... < t_{p} = 1). \end{aligned}$ 

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The directed structure of a  $\delta$ -space: a path *a* is distinguished, or allowed, if  $L(a) < \infty$ (a consequence of the weighted structure).

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DAT arose in the 1990's ([Gr], 2009; downloadable)

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General aim: modelling (possibly) non-reversible phenomena.

Intended applications: domains where privileged directions appear:

- concurrent processes,
- traffic networks,
- space-time models,
- rewrite systems, etc.

A basic setting and the most used one:

- p**Top**: category of *preordered topological spaces*,
- d**Top**: cat. of *d-spaces*, equipped with distinguished paths closed under: constant paths, concatenation, partial reparam.

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- $\mathrm{p}\textbf{Top} \to d\textbf{Top}$
- $\delta \mathsf{Mtr} o \mathrm{d}\mathsf{Top}$
- $\delta \mathbf{Mtr} o \mathbf{pTop}$

distinguished paths: the monotone ones, distinguished paths:  $L(a) < \infty$ , preorder:  $x \prec x'$  if  $\delta(x, x') < \infty$ .

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Remarks: the p-space associated to  $\delta S^n (n \ge 1)$  has no interest (chaotic preorder),

the associated d-space  $\uparrow \mathbb{S}^n$  is important

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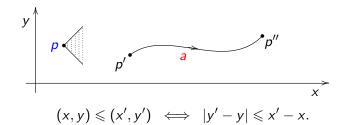
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Other settings: cubical sets, inequilogical spaces, flows, etc.

### 4. DAT: elementary examples in p**Top**

Euclidean plane  $\mathbb{R}^2$  with order relation:

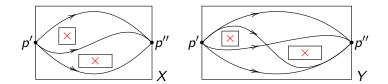


- cone of the future at the point p (the set of points  $\geq p$ ),
- directed path a from p' to p'' (a monotone map  $[0,1] \to \mathbb{R}^2$ ),

- there is no (directed) path from p'' to p',
- every loop is constant.

4A. DAT: elementary examples in p**Top**, continued

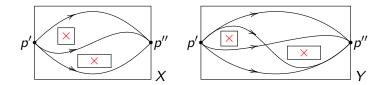
Two subspaces X, Y, with directed paths from p' to p''



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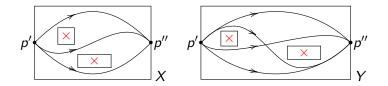
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Two subspaces X, Y, with directed paths from p' to p''



Their fundamental categories have 3 or 4 arrows  $p' \rightarrow p''$ arrows of  $\uparrow \Pi_1(-)$ : homotopy classes of paths (directed). Interpretations:

1. a stream with two islands; order: upper bound for relative v, 2. time and one-dim. space, with linear obstacles; order:  $v \leq 1$ , (3. execution paths of two concurrent automata with conflict of resources; order: time progression [FGR].)

 DAT distinguishes here between obstructions which intervene essentially together or one after the other (islands, temporary obstacles, conflicts of resources).
Topology (General or Algebraic) cannot: X ≅ Y as spaces.

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4. Examples:

 $\uparrow \Pi_1(\uparrow \mathbb{S}^1) = a$  subcategory of the groupoid  $\Pi_1(\mathbb{S}^1)$ ,  $\uparrow H_1(\uparrow \mathbb{S}^1) = (\mathbb{Z}, \leq)$ , ordered abelian group. 5. Something on Weighted Algebraic Topology

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 $\delta$ **Mtr**: category of  $\delta$ -spaces and weak contractions,

**wTop**: category of *w-spaces and cost-decreasing maps* 

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Forgetful functors:

$$\begin{split} \delta \mathsf{Mtr} &\to w \mathsf{Top}: \qquad w(a) = L(a), \\ w \mathsf{Top} &\to d \mathsf{Top}: \qquad \text{distinguished paths: } w(a) < \infty, \\ \delta \mathsf{Mtr} &\to d \mathsf{Top}: \qquad \text{distinguished paths: } L(a) < \infty. \end{split}$$

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Gelfand duality:  $C: \operatorname{HCmp} \to \operatorname{UComC^*Alg^{op}}$ , equivalence of cat.  $C(X) = \operatorname{Top}(X, \mathbb{C})$ , unital commutative C\*-algebra.

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An example:  $\vartheta$  is an irrational number.  $G_{\vartheta} = \mathbb{Z} + \vartheta \mathbb{Z}$ : ordered subgroup of  $\mathbb{R}$ ; acts on  $\mathbb{R}$  by translations (algebraically isomorphic to  $\mathbb{Z}^2$ , but totally ordered). Orbit space  $\mathbb{R}/G_{\vartheta}$ : chaotic topology ( $G_{\vartheta}$  dense in  $\mathbb{R}$ ).

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This 'object' should have  $H_1$  generated by two cycles, of length 1 and  $\vartheta!$  (Non-trivial and independent in DAT and WAT).

6A. Interpretation in Non-commutative Geometry

This trivial space is replaced by a non-commutative C\*-algebra:  $A_{\vartheta}$ : the *irrational rotation algebra* associated with  $\vartheta$ generated by two unitary elements u, v:  $vu = \exp(2\pi\vartheta).uv$ .

Also called a *noncommutative torus*: K-groups of the torus.

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Also called a *noncommutative torus*: K-groups of the torus.

Classifications (up to isomorphism or strong Morita equivalence):

$$A_{\vartheta} \cong A_{\vartheta'} \iff \vartheta' \in \pm \vartheta + \mathbb{Z},$$

 $A_{\vartheta} \sim_M A_{\vartheta'}$ : also characterised by fractional action of 2×2 matrices with integral entries.

This trivial space is replaced by a w-space:

 $W_{\vartheta} = \mathrm{w}\mathbb{R}/G_{\vartheta}$ : the *irrational rotation w-space* associated with  $\vartheta$ 

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Classifications (up to isometric or Lipschitz isomorphism):

 $\begin{array}{ll} W_{\vartheta} \cong W_{\vartheta'} & (\text{in w} \mathbf{Top}) & \Longleftrightarrow & \vartheta' \in \pm \vartheta + \mathbb{Z}, \\ W_{\vartheta} \cong {}_{\infty} W_{\vartheta'} & (\text{in w}_{\infty} \mathbf{Top}) & \Longleftrightarrow & A_{\vartheta} {}_{\sim M} A_{\vartheta'}. \end{array}$ 

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In DAT we only have the second classification, by *irrational rotation* d-spaces:

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- DAT gives a 'Non-commutative Topology', without weights.

- The quotient  $\delta \mathbb{R}/G_{\vartheta}$  has the chaotic  $\delta$ -metric and topology.

# 7. References

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