

MAX PLANCK INSTITUTE
FOR MATHEMATICS IN THE SCIENCES



Khovanskii bases and how to use them

Max Planck Institute for Mathematics in the Sciences

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25 May 2023

1 KHOVANSKII BASIS

2 MOTIVATIONS

3 SOLVING POLYNOMIAL EQUATIONS

LET'S PUT SOME ORDER IN MONOMIALS

Why do we write $x^3y^2 + 2x^2y - x + y + 2$

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Def. A *term order* in the polynomial ring $S = k[x_1, \dots, x_n]$ is a total order \leq on the set of monomials of S such that:

- ① \leq is reflexive, antisymmetric and transitive and total: for each m_1, m_2 monomials then $m_1 \leq m_2$ or $m_2 \leq m_1$ (total order).
- ② If $m_1 \leq m_2$ then $m \cdot m_1 \leq m \cdot m_2$ for every monomial m (compatible with multiplication).
- ③ If $m_1 \mid m_2$ then $m_1 \leq m_2$ ($\stackrel{(2)}{\iff} 1 \leq m$ for every monomial m).

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Condition (3) guarantees that every descending chain of monomials is finite \Rightarrow induction over "the biggest" term of a polynomial.

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Now we consider $k[x_1, \dots, x_n]$ and we write $x^\alpha := x_1^{\alpha_1} \cdots x_n^{\alpha_n}$, $\alpha \in \mathbb{N}^n$. $x_1 > x_2 > \cdots > x_n$

Lexicographic

$x^\alpha \leq_{\text{Lex}} x^\beta$ iff:

$$\alpha_1 < \beta_1 \text{ or}$$

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INITIAL TERM

Def. Given $f = \sum c_\alpha x^\alpha \in k[x_1, \dots, x_n]$, $f \neq 0$, and a term order \leq we define the *initial term* of f as:

$$\text{in}_{\leq}(f) = \max\{x^\alpha \mid x^\alpha \in \text{Supp}(f)\}.$$

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Es. $x > y > z > t$

- $\text{in}_{\text{Lex}}(x^3t + xy^3 - xy^2zt) = x^3t.$
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INITIAL ALGEBRA

Let $S = k[x_1, \dots, x_n]$ be the polynomial ring.

Def. A *polynomial algebra* generated by $\mathcal{F} \subseteq S$ is a subset of the polynomial ring $R \subseteq S$

$$R = \{p(f_1, \dots, f_s) \mid s \in \mathbb{N}, p \in k[t_1, \dots, t_s], f_1, \dots, f_s \in \mathcal{F}\}.$$

We write $R = k[\mathcal{F}]$, or $k[f_1, \dots, f_s]$ if \mathcal{F} is finite and in this case we say that R is *finitely generated*.

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- 1 $R = k[x + y + z, xy + xz + yz, xyz]$, $\text{in}(R) = k[x, xy, xyz]$.
- 2 $R = k[x + y, xy, xy^2]$, $\text{in}(R) = k[x, xy, xy^2, \dots, xy^n, \dots]$.

WHAT IS A KHOVANSKII BASIS?

Def. Let R be a finitely generated algebra in $k[x_1, \dots, x_n]$. A subset $\mathcal{F} \subseteq R$ is a *Khovanskii basis* for a term order \leq if

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Es.

- 1 F.g. polynomial algebras in 1 variable have a finite Khovanskii basis
- 2 Polynomial algebras f.g. by monomials have a finite Khovanskii basis.
- 3 Elementary symmetric polynomials form a Khovanskii basis for the ring of symmetric polynomials:

$$S^{S_n} = k[x_1 + \dots + x_n, x_1x_2 + \dots + x_{n-1}x_n, \dots, x_1 \cdots x_n].$$

Bad news: Finite Khovanskii bases do NOT always exist.

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Es. The invariant ring of the alternating group A_n , that is

$$S^{A_n} = k[x_1 + \cdots + x_n, \dots, x_1 \cdots x_n, \prod_{i < j} (x_j - x_i)],$$

does not admit a finite Khovanskii basis with respect to any term order for every $n \geq 3$ (Göbel).

ALGORITHM

SUBDUCTION ALGORITHM

Input: A Khovanskii basis \mathcal{F} for R and $f \in S$.

Output:

- If $f \in R$: A constant and an expression of f as a polynomial in the elements of \mathcal{F} .
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Is \mathcal{F} A K.B.?

$\mathcal{F} = \{f_1, \dots, f_s\} \subseteq R$.

$$\varphi : k[t_1, \dots, t_s] \longrightarrow \text{in}(R), \quad \varphi(t_i) = \text{in}(f_i).$$

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Theorem. Consider $\ker(\varphi) = (g_1, \dots, g_d)$. Then \mathcal{F} is a Khovanskii basis if and only if the subduction algorithm applied to $g_i(f_1, \dots, f_s)$ gives a constant for each i .

HILBERT FUNCTION

Def. The *Hilbert function* of a \mathbb{Z} -graded k -algebra $R = \bigoplus_{d \in \mathbb{Z}} R_d$ is

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Theorem. The Hilbert function can be expressed with a polynomial. There exists a polynomial $\text{HP}_R(t) \in \mathbb{Q}[t]$ such that $\text{HF}_R(d) = \text{HP}_R(d)$ for $d \geq d_0$. The integer d_0 is the *Hilbert regularity* of R .

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Theorem. A polynomial algebra R and its initial algebra have the same Hilbert function:

$$\mathrm{HF}_R(d) = \mathrm{HF}_{\mathrm{in}(R)}(d), \quad \text{for all } d \in \mathbb{Z}.$$

As a consequence, we get an easy way to compute a k -basis for R_d .

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If $R = k[\phi_0, \dots, \phi_\ell] \subseteq k[x_1, \dots, x_n]$, where $\{\phi_0, \dots, \phi_\ell\}$ is a Khovanskii basis w.r.t. \leq , we define:

$$A = \{\alpha_i \mid \text{in}_{\leq}(\phi_i) = x^{\alpha_i}\},$$
$$d \cdot A = \{\alpha_{i_1} + \dots + \alpha_{i_d} \mid \alpha_{i_j} \in A\}.$$

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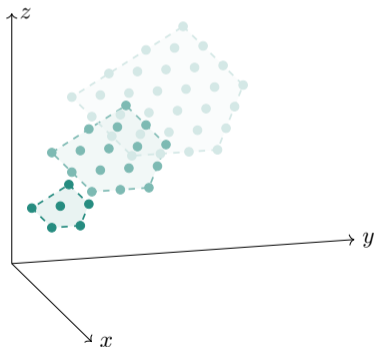
Each element in a basis of R_d corresponds to an element in $d \cdot A$:

$$R_d = \langle b_{d,\beta} \mid \beta \in d \cdot A \rangle_K,$$

where $b_{d,\beta} = \phi_{i_1} \cdots \phi_{i_d}$ and $0 \leq i_1 \leq \dots \leq i_d \leq \ell$ are integers such that $\alpha_{i_1} + \dots + \alpha_{i_d} = \beta$.

EXAMPLE: DEL PEZZO SURFACE

- $R = k[x - y, y^2 - y, xy - y, x^2 - y, xy^2 - y, x^2y - y]$
- $\text{in}(R) = k[x, y^2, xy, x^2, xy^2, x^2y]$
- $A = \{(1, 0), (0, 2), (1, 1), (2, 0), (1, 2), (2, 1)\}$
- $2 \cdot A = \{(2, 0), (1, 2), (2, 1), \dots\}$
- $R_2 = \langle (x - y)^2, (x - y)(y^2 - y), (x - y)(xy - y), \dots \rangle$



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- 4 New project computationally possible thanks to Khovansii Basis with M. Panizzut and S. Telen.

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MAIN PROBLEM

We consider the problem of finding

$$z \in K^n \quad \text{such that} \quad f_1(z) = \cdots = f_s(z) = 0,$$

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Let $\phi_0, \dots, \phi_\ell \in K[t_1, \dots, t_n]$ be a different list of polynomials and let $d_1, \dots, d_s \in \mathbb{N}^*$ be positive integers such that:

$$f_i(t) = \sum_{|\alpha|=d_i} c_{i,\alpha} \phi_0(t)^{\alpha_0} \phi_1(t)^{\alpha_1} \cdots \phi_\ell(t)^{\alpha_\ell}, \quad i = 1, \dots, s.$$

We are "forcing" f_i to be homogeneous.

OUR POINT OF VIEW

We reformulate the problem considering the *unirational variety* X obtained by the closed image of the map

$$\phi : K^n \dashrightarrow \mathbb{P}_K^\ell, \quad t \mapsto (\phi_0(t) : \cdots : \phi_\ell(t))$$

$$X := \text{Cl}\{(\phi_0(t) : \cdots : \phi_\ell(t)) \in \mathbb{P}_K^\ell \mid t \in K^n \setminus \mathbb{V}(\phi_0, \dots, \phi_\ell)\}.$$

Now we look for the *parameterized solutions* :

$$x \in X \subset \mathbb{P}_K^\ell, \quad \text{s.t.} \quad F_1(x) = \cdots = F_s(x) = 0, \quad \text{with } F_i = \sum_{|\alpha|=d_i} c_{i,\alpha} x^\alpha.$$

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We are "replacing" the polynomials ϕ_i with new variables x_i .

EXAMPLE: OSCILLATORS

The following system of two equations in two unknowns arises from the Duffing equation modelling damped and driven oscillators (Breiding, Michałek, Monin, Telen).

$$f_1 = 1 + 3t_1 + 5t_2 + 7t_1(t_1^2 + t_2^2), \quad f_2 = 11 + 13t_1 + 17t_2 + 19t_2(t_1^2 + t_2^2).$$

In this case we have $\phi_0 = 1$, $\phi_1 = t_1$, $\phi_2 = t_2$, $\phi_3 = t_1(t_1^2 + t_2^2)$, $\phi_4 = t_2(t_1^2 + t_2^2)$ and

$$f_1 = 1 \cdot \phi_0 + 3 \cdot \phi_1 + 5 \cdot \phi_2 + 7 \cdot \phi_3$$

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EXAMPLE: OSCILLATORS

The following system of two equations in two unknowns arises from the Duffing equation modelling damped and driven oscillators (Breiding, Michałek, Monin, Telen).

$$f_1 = 1 + 3t_1 + 5t_2 + 7t_1(t_1^2 + t_2^2), \quad f_2 = 11 + 13t_1 + 17t_2 + 19t_2(t_1^2 + t_2^2).$$

In this case we have $\phi_0 = 1$, $\phi_1 = t_1$, $\phi_2 = t_2$, $\phi_3 = t_1(t_1^2 + t_2^2)$, $\phi_4 = t_2(t_1^2 + t_2^2)$ and

$$f_1 = 1 \cdot \phi_0 + 3 \cdot \phi_1 + 5 \cdot \phi_2 + 7 \cdot \phi_3$$

$$f_2 = 11 \cdot \phi_0 + 13 \cdot \phi_1 + 17 \cdot \phi_2 + 19 \cdot \phi_4.$$

The surface X is defined by 3 polynomials:

$$x_1x_4 - x_2x_3 = x_1^2x_2 + x_2^3 - x_4x_1^2 = x_1^3 + x_1x_2^2 - x_3x_0^2 = 0 \quad \text{in } \mathbb{P}^4.$$

The polynomials F_i are defined as follows:

$$F_1 = x_0 + 3x_1 + 5x_2 + 7x_3, \quad F_2 = 11x_0 + 13x_1 + 17x_2 + 19x_4.$$

KHOVANSKII-MACAULAY MATRIX

We use some matrices to compute solutions of $F_1 = \dots = F_s = 0$ working directly in $K[X]$. We call them *Khovanskii-Macaulay matrices* $M_X(d)$. In degree $d = 2$ we get the matrix $M_X(2)$

$$\begin{array}{l}
 x_0 \cdot F_1 \\
 x_1 \cdot F_1 \\
 x_2 \cdot F_1 \\
 x_3 \cdot F_1 \\
 x_4 \cdot F_1 \\
 x_0 \cdot F_2 \\
 x_1 \cdot F_2 \\
 x_2 \cdot F_2 \\
 x_3 \cdot F_2 \\
 x_4 \cdot F_2
 \end{array}
 \begin{bmatrix}
 x_0^2 & x_0x_1 & x_1^2 & x_0x_2 & x_1x_2 & x_2^2 & x_0x_3 & x_1x_3 & x_2x_3 & x_3^2 & x_0x_4 & x_2x_4 & x_3x_4 & x_4^2 \\
 1 & 3 & 0 & 5 & 0 & 0 & 7 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 1 & 3 & 0 & 5 & 0 & 0 & 7 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 1 & 3 & 5 & 0 & 0 & 7 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 1 & 3 & 5 & 7 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 3 & 0 & 1 & 5 & 7 & 0 \\
 11 & 13 & 0 & 17 & 0 & 0 & 0 & 0 & 0 & 0 & 19 & 0 & 0 & 0 \\
 0 & 11 & 13 & 0 & 17 & 0 & 0 & 0 & 19 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 11 & 13 & 17 & 0 & 0 & 0 & 0 & 0 & 19 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 11 & 13 & 17 & 0 & 0 & 0 & 19 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 13 & 0 & 11 & 17 & 0 & 19
 \end{bmatrix}.$$

For general d , the rows of $M_X(d)$ are indexed by all multiples $x^\alpha \cdot F_i$, where x^α runs over a basis of $K[X]_{d-\deg(F_i)}$. The columns are indexed by a monomial basis of $K[X]_d$.

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Theorem. Let X be an arithmetically Cohen-Macaulay variety of dimension n and $I = \langle F_1, \dots, F_n \rangle \subset K[X]$ be a homogeneous ideal with $\deg(F_i) = d_i$, such that $\dim(V_X(I)) = 0$. To solve $F_1 = \dots = F_s = 0$ we need to compute the Khovanskii-Macaulay matrix in degree $\sum_{i=1}^n d_i + \text{HReg}(K[X]) + 1$.

USING KHOVANSKII BASES

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Thanks for your attention!