## Università di Genova

# A Relatively General Introduction to General Relativity Mathematical Relativity for Pedestrians 

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## Spacetime in Classical Physics: Galilei and Newton (17th Century)

## Postulate (Principle of Relativity, Galilei 1632)

Laws of physics take the same form in every inertial frame of reference ${ }^{\text {a }}$.
${ }^{a}=$ reference frame with no acceleration ("free" particles are at rest or move with constant velocity)


## Postulate (Principle of Absolute Time, Newton 1687)

Time is absolute, i.e. $t=t^{\prime}$ for all inertial frames $\mathcal{S}, \mathcal{S}^{\prime}$.

$$
(\Rightarrow A=1 \text { and } B=0)
$$

## Proposition (Galilei Transformations)

If an observer $\mathcal{S}^{\prime}$ moves with constant speed $v$ in $x$ direction with respect to observer $\mathcal{S}$, then

$$
\begin{aligned}
t^{\prime} & =t \\
x^{\prime} & =x-v t
\end{aligned}
$$

Note: Two invariants: $\Delta t:=t_{2}-t_{1}$ and $\Delta r^{2}:=\Delta x^{2}+\Delta y^{2}+\Delta z^{2}$ for two events $\left(t_{i}, x_{i}, y_{i}, z_{i}\right)$. Summary: Space and time in Galilei-Newton Theory: $\mathbb{R} \times \mathbb{R}^{3}$ with Euclidean distance.

## Einstein's Special Theory of Relativity I: Basics

$\hookrightarrow$ Speed of light is finite. In vacuum: $c=299792458 \mathrm{~m} / \mathrm{s}$
(Rømer 1676, Huygens 1678)
$\hookrightarrow$ Around 1900, both theoretical considerations (Maxwell, Lorentz, Poincaré...) and experiments (Michelson-Morley, Fizeau...) lead to:

## Postulate (Principle of Constant Speed of Light, Einstein 1905)

The speed of light (in vacuum) is independent of the inertial frame of reference.
Together with Principle of Relativity $\Rightarrow$ Einstein's Special Theory of Relativity.


## Proposition (Lorentz Transformations; Larmor, Lorentz and Poincaré around 1900)

If an observer $\mathcal{S}^{\prime}$ moves with speed $0<v<c$ in $x$ direction with respect to observer $\mathcal{S}$, then

$$
\begin{aligned}
t^{\prime} & =\gamma(v)\left(t-v x / c^{2}\right) \\
x^{\prime} & =\gamma(v)(x-v t) \quad \text { with } \quad \gamma(v):=\left(1-v^{2} / c^{2}\right)^{-1 / 2}
\end{aligned}
$$

Note: Only invariant: $\Delta s^{2}:=-\Delta t^{2}+\Delta x^{2}+\Delta y^{2}+\Delta z^{2}!\quad \Rightarrow$ $\Rightarrow \quad$ Spacetime!

## Einstein's Special Theory of Relativity II: Geometric Formulation

In special relativity, time and space is combined in a spacetime, mathematically described by a Minkowski Space:

## Definition (Minkowski Space, Minkowski 1907)

Minkowski space is $\mathbb{M}^{4} \cong \mathbb{R}^{4}$ equipped with the non-degenerate bilinear form

$$
\eta(x, y):=\sum_{\mu, \nu=0}^{3} \eta_{\mu \nu} x^{\mu} y^{\mu}=-x^{0} y^{0}+\sum_{i=1}^{3} x^{i} y^{i} \quad \text { with } \quad \eta:=\operatorname{diag}(-1,1,1,1)
$$

Different types of vectors $x^{\mu}=\left(x^{0}, x^{1}, x^{2}, x^{3}\right)=(c t, x, y, z)$ :

$$
\begin{aligned}
& \hookrightarrow \eta(x, x)>0 \ldots \text { spacelike } \\
& \hookrightarrow \eta(x, x)<0 \ldots \text { timelike } \\
& \hookrightarrow \eta(x, x)=0 \ldots \text { lightlike }
\end{aligned}
$$

Events whose distance vector is ...


## Einstein's Special Theory of Relativity III: Time Dilation

Example: Time Dilation: Time (and length) are observer dependent:


Cock at rest in $\mathcal{S}^{\prime}$ moving with speed $0<v<c$ in $x$-direction in $\mathcal{S}$.
$\hookrightarrow$ Time between two "ticks" at $t_{1}^{\prime}$ and $t_{2}^{\prime}$ in $\mathcal{S}^{\prime}: \Delta t^{\prime}:=t_{2}^{\prime}-t_{1}^{\prime}$.
$\hookrightarrow$ Time recorded in $\mathcal{S}$ :

$$
t_{i}=\gamma(v)\left(t_{i}^{\prime}+\frac{v x_{i}^{\prime}}{c^{2}}\right) \quad \text { with } \quad \gamma(v):=\left(1-\frac{v^{2}}{c^{2}}\right)^{-1 / 2}>1
$$

Since the clock is at rest in $\mathcal{S}^{\prime}\left(x_{1}^{\prime}=x_{2}^{\prime}\right)$ the time measured in $\mathcal{S}$ is

$$
\Delta t:=t_{2}-t_{1}=\gamma(v) \Delta t^{\prime} \quad \Rightarrow \quad \frac{\Delta t}{\Delta t^{\prime}}=\gamma(v)>1
$$

$\Rightarrow$ "Moving clocks tick slower for stationary observer"!

## Definition (Proper Time)

The proper time of some timelike curve is the time measured by a clock moving on this curve.

## From Special to General: The Equivalence Principle

## Postulate (Einstein Principle of Equivalence, Einstein 1907)

In small enough regions of spacetime, the laws of physics reduce to those of special relativity
$\Rightarrow$ Natural description of spacetime such that equivalence principle holds:

- Smooth manifold $\mathcal{M}$
- Lorentzian metric $g$ on $\mathcal{M}$
(locally Euclidean)
(metric of signature $(-,+,+,+)$ on tangent space)
$\Rightarrow$ locally like Minkowski!


## Key Idea of Einstein:

Gravity should no longer be regarded as a force in the conventional sense but rather as a manifestation of the curvature of spacetime, being induced by the presence of matter.



Taken by A. Sesse (1951). Source: en.wikipedia.org

## Lorentzian Geometry I: Basics

Let $\mathcal{M}$ be a smooth manifold of dimension $d \in \mathbb{N}$.

## Definition (Pseudo-Riemannian Metric)

A pseudo-Riemannian metric on $\mathcal{M}$ is a smooth symmetric rank 2-tensor field $g \in \Gamma^{\infty}\left(T \mathcal{M}^{\otimes}{ }_{s}{ }^{2}\right)$, such that $g_{p}: T_{p} \mathcal{M} \times T_{p} \mathcal{M} \rightarrow \mathbb{R}$ is a non-degenerate symmetric bilinear form for each $p \in T_{p} \mathcal{M}$.

By Sylvester's Law of Inertia (1852), for every symmetric non-degenerate bilinear form $B$ : $V \times V \rightarrow \mathbb{R}$ on a finite-dimensional $\mathbb{R}$-vector space $V$, there exists a basis such that

$$
B=\operatorname{diag}(-1, \ldots,-1,1, \ldots, 1) \quad \ldots \text { signature of } B
$$

$\hookrightarrow$ A metric $g$ of signature $(+, \ldots,+)$ is called Riemannian.
$\hookrightarrow$ A metric $g$ of signature $(-,+, \ldots,+)$ is called Lorentzian.

If $(U, \varphi)$ is a local chart of $\mathcal{M}$, locally:

$$
\left.g\right|_{U}=\sum_{\mu, \nu} g_{\mu \nu} \mathrm{d} x^{\mu} \otimes \mathrm{d} x^{\nu}
$$

for components $g_{\mu \nu} \in C^{\infty}(U)$, where $x^{\mu}:=\operatorname{pr}^{\mu} \circ \varphi$ denote the coordinates.


## Lorentzian Geometry II: Examples

## Examples of Lorentzian Manifolds:

(1) Minkowski space: $\mathcal{M} \cong \mathbb{R}^{4}$ with Minkowski metric $\eta_{p}:=\operatorname{diag}(-1,1,1,1)$ on each tangent space $T_{p} \mathcal{M} \cong \mathbb{R}^{4}$, i.e.

$$
\eta=-\mathrm{d} t \otimes \mathrm{~d} t+\sum_{i=1}^{3} \mathrm{~d} x^{i} \otimes \mathrm{~d} x^{i}
$$

(2) Let $\mathcal{M} \cong I \times \Sigma$ with $I \subset \mathbb{R}$, where $(\Sigma, h)$ is a 3D Riemannian manifold. Then

$$
g:=-N^{2} \mathrm{~d} t \otimes \mathrm{~d} t+h
$$

with $N \in C^{\infty}(\mathcal{M})$ and $N>0$ (called lapse) is a Lorentzian manifold.
$\Rightarrow$ Manifolds of this type are called globally hyperbolic.
$\Rightarrow$ Play an important role in the Cauchy problem of general relativity and in Quantum Field Theory on Curved Spacetime.
(3) In general, every non-compact and connected manifold admits a Lorentzian metric. In the compact case, there are topological obstructions:

## Example

Only spheres $\mathbb{S}^{n}$ with $n \in \mathbb{N}$ odd admit Lorentzian metrics.

## Lorentzian Geometry III: Causality

Let $(\mathcal{M}, g)$ be a Lorentzian manifold. Tangent vectors $v \in T_{p} \mathcal{M}$ can be divided as follows:

$$
\begin{aligned}
& \hookrightarrow g_{p}(v, v)>0 \ldots \text { spacelike } \\
& \hookrightarrow g_{p}(v, v)<0 \ldots \text { timelike } \\
& \hookrightarrow g_{p}(v, v)=0 \ldots \text { lightlike }
\end{aligned}
$$

Using this, we can define at every point a corresponding light cone $V_{p} \subset T_{p} \mathcal{M}$ :


A vector field $X: \mathcal{M} \rightarrow T \mathcal{M}$ is called space/time/lightlike if it is so at every point. In general, there is no global notion of time. If this is the case, $(\mathcal{M}, g)$ is called time-orientable:

## Definition (Time-Orientation)

A global timelike vector field $X$ on $\mathcal{M}$ is called "time-orientation". If such a vector field exists, $(\mathcal{M}, g)$ is called "time-orientable".

Note: Both a topological and geometrical concept!

## Lorentzian Geometry IV: Curvature

$(\mathcal{M}, g)$ has a unique connection $\nabla: \mathfrak{X}(\mathcal{M}) \times \mathfrak{X}(\mathcal{M}) \rightarrow \mathfrak{X}(\mathcal{M})$ called Levi-Civita connection.

$$
\nabla_{X} Y \ldots \text { directional derivative of } Y \text { w.r.t. } X
$$

Curvature Tensor :

$$
\operatorname{Riem}_{g}(X, Y, Z):=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z
$$

Parallel Transport: shift vector parallel along a curve

$\operatorname{Riem}\left(g_{2}\right)=0$

$$
92)-0
$$

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## Proposition

A Lorentzian manifold is flat $\left(\mathrm{Riem}_{g}=0\right)$ if and only if it is locally isometric to Minkowski space.
$\hookrightarrow$ Curvature tensor can be identified with a smooth rank 4 tensor field $\Rightarrow$ Locally: $R_{\alpha \beta \gamma \delta}$.
$\hookrightarrow$ Other important curvature tensors ( $g^{\mu \nu}$ denotes the components of the inverse metric):

$$
\begin{aligned}
\operatorname{Ric}(g)_{\mu \nu} & :=g^{\mu \nu} R_{\alpha \mu \beta \nu} \ldots \text { Ricci tensor } \\
\operatorname{Scal}(g) & :=g^{\mu \nu} \operatorname{Ric}(g)_{\mu \nu} \ldots \text { scalar curvature }
\end{aligned}
$$

## Einstein Equations

In the following, let $(\mathcal{M}, g)$ be a 4D Lorentzian manifold.

## Definition (Einstein's Field Equations, Einstein 1915)

Let $T$ be a smooth divergence-free 2-tensor field and $\Lambda \in \mathbb{R}$. Einstein's field equations are

$\hookrightarrow T$ describes the matter content. Energy-momentum conservation: $\nabla^{\lambda} T_{\lambda \nu}=0$.
$\hookrightarrow$ LOVELOCK'S THEOREM (1971): LHS is only symmetric divergent-free 2 -tensor field constructed out of $g$ involving only up to second derivatives
$\hookrightarrow$ Equations reduce to Poisson Equations of Newtonian gravity in appropriate limit.
$\Rightarrow$ Special case: Vacuum $T=0$. In this case, Einstein equations equivalent to

$$
\operatorname{Ric}(g)=\Lambda g
$$

Side Fact: $(\mathcal{M}, g)$ with $g$ such that $\operatorname{Ric}(g) \propto g$ are called Einstein manifolds.
$\hookrightarrow$ Many applications in differential geometry, but examples hard to find!
"[..] try to find one yourself [an example] which is not in our book. And if you succeed, please write to us immediately! [...] The author will be happy to stand you a meal in a starred restaurant in exchange for one of these!"

- Besse in Einstein manifolds, Springer, 1987.


## Cauchy Problem for Einstein's Equations I

Einstein's Field Equations on $\mathcal{M} \widehat{=}$ highly non-trivial 2nd order system of quasilinear PDE's for components $g_{\mu \nu}$

## Leading order contribution:

$$
\begin{aligned}
\operatorname{Ric}(g)_{\mu \nu} & -\frac{1}{2} \operatorname{Scal}(g) g_{\mu \nu}+\Lambda g_{\mu \nu}= \\
= & \frac{1}{2} \sum_{\alpha, \beta} g^{\alpha \beta}\left(\partial_{\alpha} \partial_{\nu} g_{\mu \beta}+\partial_{\mu} \partial_{\beta} g_{\alpha \nu}-\partial_{\alpha} \partial_{\beta} g_{\mu \nu}-\partial_{\mu} \partial_{\nu} g_{\alpha \beta}\right) \\
& -\frac{1}{2} g_{\mu \nu} \sum_{\alpha \beta, \rho, \sigma} g^{\alpha \beta} g^{\rho \sigma}\left(\partial_{\alpha} \partial_{\rho} g_{\sigma \beta}-\partial_{\alpha} \partial_{\beta} g_{\rho \sigma}\right) \\
& + \text { many lower order terms involving } g \text { and } \partial g .
\end{aligned}
$$

$\hookrightarrow$ neither hyperbolic, elliptic nor parabolic!
$\Rightarrow$ Key observation: Heavily overdetermined system (16 equations for 10 unknowns)
("general covariance")
$\Rightarrow$ In a clever coordinate system, Einstein equations become hyperbolic:

$$
\operatorname{Ric}(g)_{\mu \nu}=-\frac{1}{2} \square_{g}^{S} g_{\mu \nu}+\text { terms involving } g \text { and } \partial g
$$

where $\square_{g}^{S}:=g^{\alpha \beta} \nabla_{\alpha} \nabla_{\beta}$ denotes wave operator acting on scalars.

## Cauchy Problem for Einstein's Equations II

General relativity as an initial value problem:
$\hookrightarrow$ Initial Data: 3D Riemannian manifold ( $\Sigma, h$ ) and 2-tensor field $k$ on $\Sigma$, satisfying constraints.
$\hookrightarrow$ A Cauchy development of $(\Sigma, h, k)$ is a 4D Lorentzian manifold ( $\mathcal{M}, g$ ) solving Einstein's equations, such that
(1) $\mathcal{M} \cong I \times \Sigma$ with $I \subset \mathbb{R}$ ("time") and such that $\Sigma$ is a spacelike embedded hypersurface.
(2) $i^{*} g=h$ with embedding $i: \Sigma \rightarrow \mathcal{M}$ and $k$ is the extrinsic curvature of hypersurface $\Sigma$ in $\mathcal{M}$.


## Theorem (Choquet-Bruhat (1952); Choquet-Bruhat, Geroch (1969))

Let $(\Sigma, h, k)$ be an admissible set of initial data. Then there exists a Cauchy development $(\mathcal{M}, g)$, which is unique up to isometry.

Note: Unlike other PDEs formulated on fixed background we are solving for spacetime itself ! Example: Initial data $\left(\mathbb{R}^{3}, \delta, 0\right)$ leads to Minkowski space $\left(\mathbb{R}^{4}, \eta\right)$.

## The Schwarzschild Solution and Black Holes

First (vacuum) solution: Schwarzschild 1916 (during world war I): Manifold $\mathbb{R} \times \mathbb{R}_{>0} \times \mathbb{S}^{2}$ with

$$
g=-c^{2}\left(1-\frac{2 G M}{c^{2} r}\right) \mathrm{d} t \otimes \mathrm{~d} t+\left(1-\frac{2 G M}{c^{2} r}\right)^{-1} \mathrm{~d} r \otimes \mathrm{~d} r+r^{2} \mathrm{~d} \Omega_{\mathbb{S}^{2}}^{2}
$$

where $\mathrm{d} \Omega_{\mathbb{S}^{2}}^{2}$ denotes the standard Riemannian metric of the 2 -sphere $\mathbb{S}^{2}$ and $M \in \mathbb{R}>0$ a mass.
$\Rightarrow$ For $r>R$ describes gravitational field outside of a spherically symmetric object of mass $M$ and radius $R$ (star, planets, ...)

## Theorem (Birkhoff 1923)

The Schwarzschild metric is the only spherically symmetric vacuum solution with $\Lambda=0$.
Something strange happens at $r_{s}:=2 G M / c^{2}$ :


Questions: What happens if an object is so massive that its radius $R$ is $R<r_{s}$ ? $\Rightarrow$ Black Hole

## Accurate Sketch of a Black Hole

Accurate and detailed sketch of a black hole:


Source: Scholtz, Unwin: What if Planet 9 is a Primordial Black Hole? Physical Review Letters 125, 2020. Preprint: arXiv:1909.11090 [hep-th].

## Physical Evidence of Black Holes

## (1) Indirect (Genzel, Ghez et al.):


(2) Indirect (LIGO \& Virgo):

(3) Direct (EHT):


## Sources:

(1) Eisenhauer et al.: SINFONI in the Galactic Center: young stars and IR flares in the central light month. The Astrophysical Journal 628(1), pages 246-259, 2005. Preprint: arXiv:astro-ph/0502129 [astro-ph].
(2) LIGO Scientific and Virgo collaboration: Observation of Gravitational Waves from a Binary Black Hole Merger. Physical Review Letters 116, 2016. Preprint: arXiv:1602.03837 [gr-qc].
(3) The EHT collaboration: First M87 Event Horizon Telescope Results. I. The Shadow of the Supermassive Black Hole. The Astrophysical Journal Letters 875(1), 2019. Preprint: arXiv:1906.11238 [astro-ph.GA].
The EHT collaboration: First Sagittarius A* Event Horizon Telescope Results. I. The Shadow of the Supermassive Black Hole in the Center of the Milky Way. The Astrophysical Journal Letters 930(2), 2022.

## Mathematical Results: Singularity Theorems

In a Schwarzschild black hole ...
... no observer or light-ray entering the region $r<r_{s}$ can leave.
$\ldots$ any causal curve starting in region $r<r_{s}$ terminates at $r=0$ in finite proper time.
... Curvature invariants diverge at $r=0$, e.g.

$$
\left\|\operatorname{Riem}_{g}\right\|_{g}^{2}=\sum_{\alpha, \beta \gamma \delta} R^{\alpha \beta \gamma \delta} R_{\alpha \beta \gamma \delta}=\frac{12 r_{s}^{2}}{r^{6}} \xrightarrow{r \rightarrow 0} \infty
$$

$\Rightarrow$ Prototypical example of gravitational singularity!

Question: Are gravitational singularities mathematical artifacts or physical predictions?

## Theorem (Penrose 1965)

Let $(\mathcal{M}, g)$ be a solution of Einstein's equations with energy-momentum tensor $T$. Under certain (reasonable) assumptions on $T$ ("energy conditions") and certain (reasonable) causality assumptions, $(\mathcal{M}, g)$ is lightlike geodesically incomplete whenever it admits a closed trapped surface ${ }^{a}$.

[^0]Remark: Similar theorem for timelike geodesically incompleteness (Hawking 1966). (Cosmology)

## Real Life Application: GPS (Global Positioning System, 1970s)

Metric of earth can be approximated as $\left(r>R_{\oplus}\right)$


$$
g=-c^{2}\left(1+\frac{2 \Phi(r)}{c^{2}}\right) \mathrm{d} t \otimes \mathrm{~d} t+\left(1-\frac{2 \Phi(r)}{c^{2}}\right)(\mathrm{d} x \otimes \mathrm{~d} x+\mathrm{d} y \otimes \mathrm{~d} y+\mathrm{d} z \otimes \mathrm{~d} z)
$$

with gravitational potential $\Phi(r)=-G M_{\oplus} / r$ and $r=\sqrt{x^{2}+y^{2}+z^{2}}$.
$\Rightarrow$ Proper Time difference between (stationary) receiver and satellite:

$$
\frac{\Delta \tau_{r}}{\Delta \tau_{s}} \cong(1+\underbrace{\frac{\Phi\left(r_{\oplus}\right)-\Phi\left(r_{\oplus}+h\right)}{c^{2}}}_{\text {gravitational time dilation }}+\underbrace{\frac{1}{2} \frac{v^{2}}{c^{2}}}_{\text {special relativistic time dilation }})
$$

Example: Satellite with $\mathrm{v}=14000 \mathrm{~km} / \mathrm{h}$ and $\mathrm{h}=20200 \mathrm{~km}$. After one day on earth $\left(\Delta \tau_{r}=24 \mathrm{~h}\right)$ :

$$
\delta \tau=\Delta \tau_{r}-\Delta \tau_{s} \cong-38.5 \mu \mathrm{~s}= \begin{cases}-45.7 \mu \mathrm{~s} & \text { gravitational time dilation } \\ +7.3 \mu \mathrm{~s} & \text { special relativistic time dilation }\end{cases}
$$

$\Rightarrow$ Without taking $\delta \tau$ into account, we have a distance deviation of $|c \cdot \delta \tau| \cong 11.5 \mathrm{~km}$ per day!

## Conclusion and Outlook

$\hookrightarrow$ General relativity is a well-established theory with many applications in physics, pure mathematics and in our daily life.
$\hookrightarrow$ Many more topics and applications (Numerical Relativity, Cosmology, ...)
$\hookrightarrow$ General relativity is not the end of the story!
$\Rightarrow$ not compatible with the "second half of modern physics": Quantum Field Theory
$\Rightarrow$ The ultimate quest for a

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Quantum Theory of Gravity.
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$\Rightarrow$ Many candidates: (partially related)

- String Theory
- Loop Quantum Gravity
- Spin Foam Models
- Group Field Theory
- ...
- Matrix and Tensor Models
- Simplicial Quantum Gravity
- Causal Dynamical Triangulation
- Causal Set Theory
- Causal Fermion Systems
- Asymptotic Safety for Gravity
- Noncommutative Geometry
- Twistor Theory
$\Rightarrow$ Many open questions. One Step back: Perturbative Quantum Gravity (=linearized gravity as perturbative quantum field theory), Semiclassical Gravity, Quantum Field Theory on Curved Spacetime, . . .
"In so far as theories of mathematics speak about reality, they are not certain, and in so far as they are certain, they do not speak about reality."
- Einstein in Geometrie und Erfahrung, Springer, 1921.


[^0]:    ${ }^{a}$ Roughly speaking: surface where the gravitational field is so strong that outgoing photons are dragged inwards.

