

# A Relatively General Introduction to General Relativity

Mathematical Relativity for Pedestrians

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# Spacetime in Classical Physics: Galilei and Newton (17th Century)

### Postulate (Principle of Relativity, Galilei 1632)

Laws of physics take the same form in every inertial frame of reference<sup>a</sup>.

<sup>a</sup> = reference frame with no acceleration ("free" particles are at rest or move with constant velocity)

Postulate (Principle of Absolute Time, Newton 1687)

Time is *absolute*, i.e. t = t' for all inertial frames S, S'.

### Proposition (Galilei Transformations)

If an observer  $\mathcal{S}'$  moves with constant speed v in x direction with respect to observer  $\mathcal{S}$ , then

$$t' = t$$
$$x' = x - vt$$

Note: Two invariants:  $\Delta t := t_2 - t_1$  and  $\Delta r^2 := \Delta x^2 + \Delta y^2 + \Delta z^2$  for two events  $(t_i, x_i, y_i, z_i)$ . Summary: Space and time in GALILEI-NEWTON THEORY:  $\mathbb{R} \times \mathbb{R}^3$  with Euclidean distance.

 $(\Rightarrow A = 1 \text{ and } B = 0)$ 

# Einstein's Special Theory of Relativity I: Basics

- $\hookrightarrow$  Speed of light is *finite*. In vacuum:  $c = 299\,792\,458\,\mathrm{m/s}$  (Rømer 1676, Huygens 1678)
- $\hookrightarrow$  Around 1900, both theoretical considerations (Maxwell, Lorentz, Poincaré...) and experiments (Michelson-Morley, Fizeau...) lead to:

### Postulate (Principle of Constant Speed of Light, Einstein 1905)

The speed of light (in vacuum) is independent of the inertial frame of reference.

Together with PRINCIPLE OF RELATIVITY  $\Rightarrow$  EINSTEIN'S SPECIAL THEORY OF RELATIVITY.



Proposition (Lorentz Transformations; Larmor, Lorentz and Poincaré around 1900)

If an observer S' moves with speed 0 < v < c in x direction with respect to observer S, then  $t' = \gamma(v)(t - vx/c^2)$ 

$$x' = \gamma(v)(x - vt)$$
 with  $\gamma(v) := (1 - v^2/c^2)^{-1/2}$ 

**Note**: Only invariant:  $\Delta s^2 := -\Delta t^2 + \Delta x^2 + \Delta y^2 + \Delta z^2!$ 

 $\Rightarrow$ 

# Einstein's Special Theory of Relativity II: Geometric Formulation

In special relativity, time and space is combined in a *spacetime*, mathematically described by a MINKOWSKI SPACE:

### Definition (Minkowski Space, Minkowski 1907)

Minkowski space is  $\mathbb{M}^4\cong\mathbb{R}^4$  equipped with the non-degenerate bilinear form

$$\eta(x,y) := \sum_{\mu,\nu=0}^{3} \eta_{\mu\nu} x^{\mu} y^{\mu} = -x^{0} y^{0} + \sum_{i=1}^{3} x^{i} y^{i} \qquad \text{ with } \qquad \eta := \text{diag}(-1,1,1,1).$$

Different types of vectors  $x^{\mu} = (x^0, x^1, x^2, x^3) = (ct, x, y, z)$ :  $\hookrightarrow \eta(x, x) > 0 \dots$  spacelike  $\hookrightarrow \eta(x, x) < 0 \dots$  timelike  $\hookrightarrow \eta(x, x) = 0 \dots$  lightlike

Events whose distance vector is ...

- ... spacelike are *causally disconnected*.
- ... timelike/lightlike are causally connected.



# Einstein's Special Theory of Relativity III: Time Dilation

**Example:** <u>Time Dilation</u>: Time (and length) are observer dependent:



Cock at rest in S' moving with speed 0 < v < c in *x*-direction in S.  $\hookrightarrow$  Time between two "ticks" at  $t'_1$  and  $t'_2$  in S':  $\Delta t' := t'_2 - t'_1$ .

 $\hookrightarrow$  Time recorded in S:

$$t_i = \gamma(v) \left( t'_i + \frac{vx'_i}{c^2} \right) \qquad \text{with} \qquad \gamma(v) := \left( 1 - \frac{v^2}{c^2} \right)^{-1/2} > 1$$

Since the clock is at rest in  $\mathcal{S}'$   $(x_1' = x_2')$  the time measured in  $\mathcal{S}$  is

$$\Delta t := t_2 - t_1 = \gamma(v) \Delta t' \qquad \Rightarrow \qquad \frac{\Delta t}{\Delta t'} = \gamma(v) > 1$$

 $\Rightarrow$  "Moving clocks tick slower for stationary observer"!

### Definition (Proper Time)

The proper time of some timelike curve is the time measured by a clock moving on this curve.

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# From Special to General: The Equivalence Principle

### Postulate (Einstein Principle of Equivalence, Einstein 1907)

In small enough regions of spacetime, the laws of physics reduce to those of special relativity

 $\Rightarrow$  Natural description of spacetime such that equivalence principle holds:

- Smooth manifold  $\mathcal{M}$
- Lorentzian metric g on  $\mathcal{M}$

(metric of signature (-, +, +, +) on tangent space)

 $\Rightarrow$  locally like Minkowski!

(locally Euclidean)

### Key Idea of Einstein:

Gravity should no longer be regarded as a force in the conventional sense but rather as a manifestation of the curvature of spacetime, being induced by the presence of matter.





Taken by A. Sesse (1951). Source: en.wikipedia.org

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### Lorentzian Geometry I: Basics

Let  $\mathcal{M}$  be a smooth manifold of dimension  $d \in \mathbb{N}$ .

### Definition (Pseudo-Riemannian Metric)

A pseudo-Riemannian metric on  $\mathcal{M}$  is a smooth symmetric rank 2-tensor field  $g \in \Gamma^{\infty}(T\mathcal{M}^{\otimes_s 2})$ , such that  $g_p: T_p\mathcal{M} \times T_p\mathcal{M} \to \mathbb{R}$  is a non-degenerate symmetric bilinear form for each  $p \in T_p\mathcal{M}$ .

By SYLVESTER'S LAW OF INERTIA (1852), for every symmetric non-degenerate bilinear form  $B : V \times V \to \mathbb{R}$  on a finite-dimensional  $\mathbb{R}$ -vector space V, there exists a basis such that

 $B = diag(-1, \dots, -1, 1, \dots, 1)$  ... signature of B

 $\hookrightarrow$  A metric g of signature  $(+, \ldots, +)$  is called *Riemannian*.

 $\hookrightarrow$  A metric g of signature  $(-, +, \dots, +)$  is called *Lorentzian*.

If  $(U, \varphi)$  is a local chart of  $\mathcal{M}$ , locally:

$$g|_U = \sum_{\mu,
u} g_{\mu
u} \mathrm{d} x^\mu \otimes \mathrm{d} x^
u$$

for components  $g_{\mu\nu} \in C^{\infty}(U)$ , where  $x^{\mu} := pr^{\mu} \circ \varphi$  denote the coordinates.



# Lorentzian Geometry II: Examples

### Examples of Lorentzian Manifolds:

(1) Minkowski space:  $\mathcal{M} \cong \mathbb{R}^4$  with Minkowski metric  $\eta_p := \operatorname{diag}(-1, 1, 1, 1)$  on each tangent space  $T_p \mathcal{M} \cong \mathbb{R}^4$ , i.e.

$$\eta = -\mathrm{d}t \otimes \mathrm{d}t + \sum_{i=1}^3 \mathrm{d}x^i \otimes \mathrm{d}x^i.$$

(2) Let  $\mathcal{M} \cong I \times \Sigma$  with  $I \subset \mathbb{R}$ , where  $(\Sigma, h)$  is a 3D Riemannian manifold. Then

$$g := -N^2 \mathrm{d}t \otimes \mathrm{d}t + h$$

with  $N \in C^{\infty}(\mathcal{M})$  and N > 0 (called *lapse*) is a Lorentzian manifold.

- $\Rightarrow$  Manifolds of this type are called *globally hyperbolic*.
- ⇒ Play an important role in the Cauchy problem of general relativity and in QUANTUM FIELD THEORY ON CURVED SPACETIME.
- (3) In general, every non-compact and connected manifold admits a Lorentzian metric. In the compact case, there are topological obstructions:

### Example

Only spheres  $\mathbb{S}^n$  with  $n\in\mathbb{N}$  odd admit Lorentzian metrics.

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# Lorentzian Geometry III: Causality

Let  $(\mathcal{M},g)$  be a Lorentzian manifold. Tangent vectors  $v \in T_p\mathcal{M}$  can be divided as follows:

 $\begin{array}{l} \hookrightarrow \ g_p(v,v) > 0 \dots \textit{spacelike} \\ \hookrightarrow \ g_p(v,v) < 0 \dots \textit{timelike} \\ \hookrightarrow \ g_p(v,v) = 0 \dots \textit{lightlike} \end{array}$ 

Using this, we can define at every point a corresponding light cone  $V_p \subset T_p \mathcal{M}$ :



A vector field  $X : \mathcal{M} \to T\mathcal{M}$  is called space/time/lightlike if it is so at every point. In general, there is no *global* notion of time. If this is the case,  $(\mathcal{M}, g)$  is called *time-orientable*:



# Lorentzian Geometry IV: Curvature

 $(\mathcal{M},g)$  has a unique connection  $\nabla: \mathfrak{X}(\mathcal{M}) \times \mathfrak{X}(\mathcal{M}) \to \mathfrak{X}(\mathcal{M})$  called *Levi-Civita connection*.  $\nabla_X Y \dots$  directional derivative of Y w.r.t. X



### Proposition

A Lorentzian manifold is flat  $(\text{Riem}_g = 0)$  if and only if it is locally isometric to Minkowski space.

 $\hookrightarrow$  Curvature tensor can be identified with a smooth rank 4 tensor field  $\Rightarrow$  Locally:  $R_{\alpha\beta\gamma\delta}$ .

 $\hookrightarrow$  Other important curvature tensors ( $g^{\mu
u}$  denotes the components of the inverse metric):

$$\operatorname{Ric}(g)_{\mu\nu} := g^{\mu\nu} R_{\alpha\mu\beta\nu} \dots \operatorname{Ricci} \operatorname{tensor}$$
$$\operatorname{Scal}(g) := g^{\mu\nu} \operatorname{Ric}(g)_{\mu\nu} \dots \operatorname{scalar} \operatorname{curvature}$$

# **Einstein Equations**

In the following, let  $(\mathcal{M}, g)$  be a 4D Lorentzian manifold.

### Definition (Einstein's Field Equations, Einstein 1915)

Let T be a smooth divergence-free 2-tensor field and  $\Lambda \in \mathbb{R}.$  Einstein's field equations are

 $\underbrace{\operatorname{Ric}(g) - \frac{1}{2}\operatorname{Scal}(g)g + \Lambda g}_{\textit{curvature of spacetime}} = \underbrace{\frac{8\pi G}{c^4}T}_{\textit{matter content}}$ 

- $\hookrightarrow$  T describes the matter content. Energy-momentum conservation:  $\nabla^{\lambda}T_{\lambda\nu} = 0$ .
- $\hookrightarrow$  LOVELOCK'S THEOREM (1971): LHS is only symmetric divergent-free 2-tensor field constructed out of g involving only up to second derivatives
- $\hookrightarrow$  Equations reduce to POISSON EQUATIONS of Newtonian gravity in appropriate limit.
- $\Rightarrow$  Special case: Vacuum T = 0. In this case, Einstein equations equivalent to

$$\operatorname{Ric}(g) = \Lambda g$$

Side Fact:  $(\mathcal{M}, g)$  with g such that  $\operatorname{Ric}(g) \propto g$  are called *Einstein manifolds*.

 $\,\hookrightarrow\,$  Many applications in differential geometry, but examples hard to find!

"[...] try to find one yourself [an example] which is not in our book. And if you succeed, please write to us immediately! [...] The author will be happy to stand you a meal in a starred restaurant in exchange for one of these!"

- Besse in Einstein manifolds, Springer, 1987.

# Cauchy Problem for Einstein's Equations I

Einstein's Field Equations on  $\mathcal{M} \cong$  highly non-trivial 2nd order system of quasilinear PDE's for components  $g_{\mu\nu}$ 

### Leading order contribution:

$$\begin{split} \operatorname{Ric}(g)_{\mu\nu} &- \frac{1}{2} \operatorname{Scal}(g) g_{\mu\nu} + \Lambda g_{\mu\nu} = \\ &= \frac{1}{2} \sum_{\alpha,\beta} g^{\alpha\beta} (\partial_{\alpha} \partial_{\nu} g_{\mu\beta} + \partial_{\mu} \partial_{\beta} g_{\alpha\nu} - \partial_{\alpha} \partial_{\beta} g_{\mu\nu} - \partial_{\mu} \partial_{\nu} g_{\alpha\beta}) \\ &- \frac{1}{2} g_{\mu\nu} \sum_{\alpha\beta,\rho,\sigma} g^{\alpha\beta} g^{\rho\sigma} (\partial_{\alpha} \partial_{\rho} g_{\sigma\beta} - \partial_{\alpha} \partial_{\beta} g_{\rho\sigma}) \\ &+ many \ lower \ order \ terms \ involving \ g \ and \ \partial g. \end{split}$$

 $\hookrightarrow$  neither hyperbolic, elliptic nor parabolic!

 $\Rightarrow$  Key observation: Heavily overdetermined system (16 equations for 10 unknowns)

("general covariance")

 $\Rightarrow$  In a clever coordinate system, Einstein equations become hyperbolic:

$$\operatorname{Ric}(g)_{\mu\nu} = -\frac{1}{2} \Box_g^S g_{\mu\nu} + \text{terms involving } g \text{ and } \partial g.$$

where  $\Box_g^S := g^{\alpha\beta} \nabla_{\alpha} \nabla_{\beta}$  denotes wave operator acting on scalars.

# Cauchy Problem for Einstein's Equations II

General relativity as an initial value problem:

- $\hookrightarrow \text{ Initial Data: 3D Riemannian manifold } (\Sigma, h) \text{ and } 2\text{-tensor field } k \text{ on } \Sigma \text{, satisfying constraints.}$
- $\hookrightarrow$  A Cauchy development of  $(\Sigma,h,k)$  is a 4D Lorentzian manifold  $(\mathcal{M},g)$  solving Einstein's equations, such that
  - (1)  $\mathcal{M} \cong I \times \Sigma$  with  $I \subset \mathbb{R}$  ("time") and such that  $\Sigma$  is a spacelike embedded hypersurface.
  - (2)  $i^*g = h$  with embedding  $i: \Sigma \to \mathcal{M}$  and k is the *extrinsic curvature* of hypersurface  $\Sigma$  in  $\mathcal{M}$ .



### Theorem (Choquet-Bruhat (1952); Choquet-Bruhat, Geroch (1969))

Let  $(\Sigma, h, k)$  be an admissible set of initial data. Then there exists a Cauchy development  $(\mathcal{M}, g)$ , which is unique up to isometry.

**Note**: Unlike other PDEs formulated on fixed background we are solving for *spacetime itself*! **Example**: Initial data  $(\mathbb{R}^3, \delta, 0)$  leads to Minkowski space  $(\mathbb{R}^4, \eta)$ .

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PhD Seminars

# The Schwarzschild Solution and Black Holes

**First (vacuum) solution:** Schwarzschild 1916 (during world war I): Manifold  $\mathbb{R} \times \mathbb{R}_{>0} \times \mathbb{S}^2$  with

$$g = -c^2 \left(1 - \frac{2GM}{c^2 r}\right) \mathrm{d}t \otimes \mathrm{d}t + \left(1 - \frac{2GM}{c^2 r}\right)^{-1} \mathrm{d}r \otimes \mathrm{d}r + r^2 \mathrm{d}\Omega_{\mathbb{S}^2}^2,$$

where  $d\Omega_{s2}^2$  denotes the standard Riemannian metric of the 2-sphere  $\mathbb{S}^2$  and  $M \in \mathbb{R}_{>0}$  a mass.

 $\Rightarrow$  For r > R describes gravitational field outside of a spherically symmetric object of mass M and radius R (star, planets, ...)

Theorem (Birkhoff 1923)

The Schwarzschild metric is the only spherically symmetric vacuum solution with  $\Lambda = 0$ .

Something strange happens at  $r_s := 2GM/c^2$ :

(sun:  $r_s \cong 3 \,\mathrm{km} \ll R \cong 670\,000 \,\mathrm{km}$ )



Questions: What happens if an object is so massive that its radius R is  $R < r_s? \Rightarrow$  Black Hole

# Accurate Sketch of a Black Hole

### Accurate and detailed sketch of a black hole:

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### SUPPLEMENTARY MATERIAL



Source: Scholtz, Unwin: *What if Planet 9 is a Primordial Black Hole?* Physical Review Letters 125, 2020. Preprint: arXiv:1909.11090 [hep-th].

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# Physical Evidence of Black Holes

(1) Indirect (Genzel, Ghez et al.):

### (2) Indirect (LIGO & Virgo): (3) Direct (EHT):



# Gyr A<sup>r</sup>

### Sources:

- Eisenhauer et al.: SINFONI in the Galactic Center: young stars and IR flares in the central light month. The Astrophysical Journal 628(1), pages 246-259, 2005. Preprint: arXiv:astro-ph/0502129 [astro-ph].
- (2) LIGO Scientific and Virgo collaboration: Observation of Gravitational Waves from a Binary Black Hole Merger. Physical Review Letters 116, 2016. Preprint: arXiv:1602.03837 [gr-qc].
- (3) The EHT collaboration: First M87 Event Horizon Telescope Results. I. The Shadow of the Supermassive Black Hole. The Astrophysical Journal Letters 875(1), 2019. Preprint: arXiv:1906.11238 [astro-ph.GA].

The EHT collaboration: First Sagittarius A\* Event Horizon Telescope Results. I. The Shadow of the Supermassive Black Hole in the Center of the Milky Way. The Astrophysical Journal Letters 930(2), 2022.

# Mathematical Results: Singularity Theorems

In a Schwarzschild black hole ...

- $\ldots$  no observer or light-ray entering the region  $r < r_s$  can leave.
- $\dots$  any causal curve starting in region  $r < r_s$  terminates at r = 0 in finite proper time.
- ... Curvature invariants diverge at r = 0, e.g.

$$\|\operatorname{Riem}_g\|_g^2 = \sum_{\alpha,\beta\gamma\delta} R^{\alpha\beta\gamma\delta} R_{\alpha\beta\gamma\delta} = \frac{12r_s^2}{r^6} \stackrel{r\to 0}{\to} \infty$$

 $\Rightarrow$  Prototypical example of gravitational singularity!

Question: Are gravitational singularities mathematical artifacts or physical predictions?

### Theorem (Penrose 1965)

Let  $(\mathcal{M}, g)$  be a solution of Einstein's equations with energy-momentum tensor T. Under certain (reasonable) assumptions on T ("energy conditions") and certain (reasonable) causality assumptions,  $(\mathcal{M}, g)$  is lightlike geodesically incomplete whenever it admits a closed trapped surface<sup>a</sup>.

<sup>a</sup>Roughly speaking: surface where the gravitational field is so strong that outgoing photons are dragged inwards.

Remark: Similar theorem for timelike geodesically incompleteness (Hawking 1966). (Cosmology)

# Real Life Application: GPS (Global Positioning System, 1970s)



Metric of earth can be approximated as  $(r > R_{\oplus})$ 

$$g = -c^2 \left(1 + \frac{2\Phi(r)}{c^2}\right) \mathrm{d}t \otimes \mathrm{d}t + \left(1 - \frac{2\Phi(r)}{c^2}\right) (\mathrm{d}x \otimes \mathrm{d}x + \mathrm{d}y \otimes \mathrm{d}y + \mathrm{d}z \otimes \mathrm{d}z)$$

with gravitational potential  $\Phi(r) = -GM_{\oplus}/r$  and  $r = \sqrt{x^2 + y^2 + z^2}$ .

⇒ Proper Time difference between (stationary) receiver and satellite:



**Example**: Satellite with v=14 000 km/h and h=20 200 km. After one day on earth ( $\Delta \tau_r = 24$  h):

$$\delta \tau = \Delta \tau_r - \Delta \tau_s \cong -38.5 \,\mu \text{s} = \begin{cases} -45.7 \,\mu \text{s} & \text{gravitational time dilation} \\ +7.3 \,\mu \text{s} & \text{special relativistic time dilation} \end{cases}$$

 $\Rightarrow$  Without taking  $\delta \tau$  into account, we have a distance deviation of  $|c \cdot \delta \tau| \cong 11.5 \, \mathrm{km}$  per day!

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# Conclusion and Outlook

- $\hookrightarrow$  General relativity is a well-established theory with many applications in *physics*, *pure mathe*matics and in our daily life.
- $\hookrightarrow$  Many more topics and applications (*Numerical Relativity, Cosmology,* ...)
- General relativity is not the end of the story!  $\rightarrow$ 
  - $\Rightarrow$  not compatible with the "second half of modern physics": QUANTUM FIELD THEORY
  - $\Rightarrow$

The ultimate quest for a QUANTUM THEORY OF GRAVITY.

- Many candidates: (partially related)  $\Rightarrow$ 
  - String Theory
  - Loop Quantum Gravity
  - Spin Foam Models
  - Group Field Theory

- Matrix and Tensor Models
- Simplicial Quantum Gravity
- Causal Dynamical Triangulation
- Causal Set Theory

- Causal Fermion Systems
- Asymptotic Safety for Gravity
- Noncommutative Geometry
- Twistor Theory

- . . .
- $\Rightarrow$  Many open guestions. One Step back: Perturbative Quantum Gravity (=linearized gravity as perturbative quantum field theory), Semiclassical Gravity, Quantum Field Theory on Curved Spacetime, ...

"In so far as theories of mathematics speak about reality, they are not certain, and in so far as they are certain, they do not speak about reality."

- Einstein in Geometrie und Erfahrung, Springer, 1921.

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